FILE

INSTRUCTIONS

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AIR CIRCUIT BREAKER

TYPES

AE-1-25, AEF-1, and AE-1-25Y1

Formerly Types AE-1B, AEF-1B, and AE-1BY1

RAW

Switchgear

GENERAL E ELECTRIC
SCHENECTADY, N.Y.

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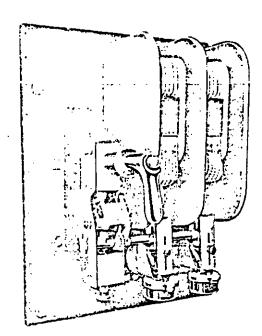


FIG. 1 MANUALLY OPERATED LIVE FRONT BREAKER.

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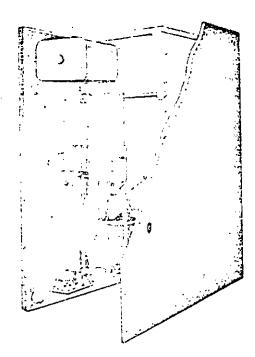
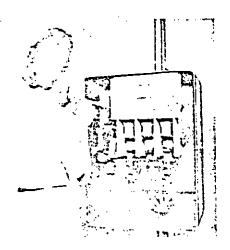


FIG. 2
ELECTRICALLY OPERATED DEAD FRONT BREAKER.



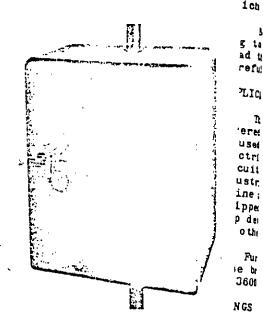
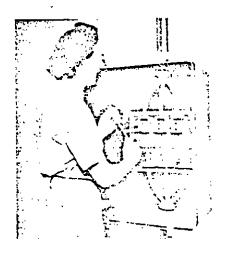


FIG. 3
MANUALLY OPERATED, ENGLOSED BREAKER.



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AIR CIRCUIT BREAKERS

TYPES AE-1-25, AEF-1, AE-1-25Y1

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

GENERAL INFORMATION

These breakers were formerly designated Type AE-1B, Type AEF-1B and Type AE-1-BY1 to which these instructions generally apply.

Before unpacking, installing or attempting to operate these air circuit breakers, read this instruction book thoroughly and carefully.

APPLICATION

The type AE-1-25 air circuit breakers covered by this instruction book are generally used for the protection and control of electrical apparatus, main feeders and branch circuits, including equipment in buildings, industries and power stations, and merchant marine application. The breakers may be equipped with a wide choice of operating and trip devices and accessories for overcurrent and other functions.

Further discussion and application of these breakers will be found in publication GET-3600.

RATINGS

Current Ratings:Up to and including 600 amperes.
Voltage Ratings:Up to and including 600 volts A-c.
Up to and including 250 volts D-c.
Interrupting Ratings:25,000 amperes.

OPERATING CHARACTERISTICS

Type AE-1-25 breakers can be furnished either live front or dead front, and either manually or electrically operated with one, two, three or four poles and with various accessories. All breakers are provided with arc quenchers to extinquish the arc after the contacts open and box type barriers are provided for dead front and enclosed breakers to confine the arc.

The breaker is closed by a toggle mechanism operated either manually, or electrically

by a solenoid, against a heavy spring between the operating mechanism and the operating shaft, upon which the movable contacts are mounted, and against springs behind the contacts. These springs supply the power to open the breaker when a latch is released manually or by tripping devices. The breaker is trip free which assures that the contacts cannot be closed as long as the latch is in the tripped position.

Current enters the breaker by the upper stud, passes through the stationary contacts, the movable contacts, the flexible connection, through the series coil and out the lower stud. When the breaker opens, the main contacts separate first which shunts the current to the arcing contacts to prevent burning of the main silver contacts as described under "Contact Assembly". When these open the current is again shunted to arc runners in series with a blowout coil which magnetically blows the arc upwards among the cooling pins and arc barriers, as described under "Arc Quenchers and Barriers", to quickly open the circuit.

SHIPPING-UNPACKING-STORAGE

TRANSPORTATION DAMAGE

Immediately upon receipt of the breakers, an examination should be made for any damage or loss sustained during transportation. If injury, rough handling, or loss is evident a damage claim should be filed at once with the transportation company and the nearest General Electric Sales Office should be promptly notified.

UNPACKING

The breakers should be unpacked as soon as possible after being received as difficulty may be experienced in making claim for damage, not evident upon receipt, if delayed. Care should be used in unpacking in order to avoid damaging any of the breaker parts. Be sure that no loose parts are missing or left in the packing material. Blow out any dirt or particles of packing material that may be accumulated on the breaker parts.

STORAGE

If the breakers are not to be mounted in their permanent locations at once, they should be stored in a clean dry place and preferably in a vertical position. They should be supported to prevent bending of studs, or damage to breaker parts. It is best not to cover the breakers with any packing material or other material that is apt to absorb moisture which may cause corrosion of breaker parts. A covering of paper will prevent dust from settling on the breaker parts and should be used if the breakers are to be stored for any considerable length of time.

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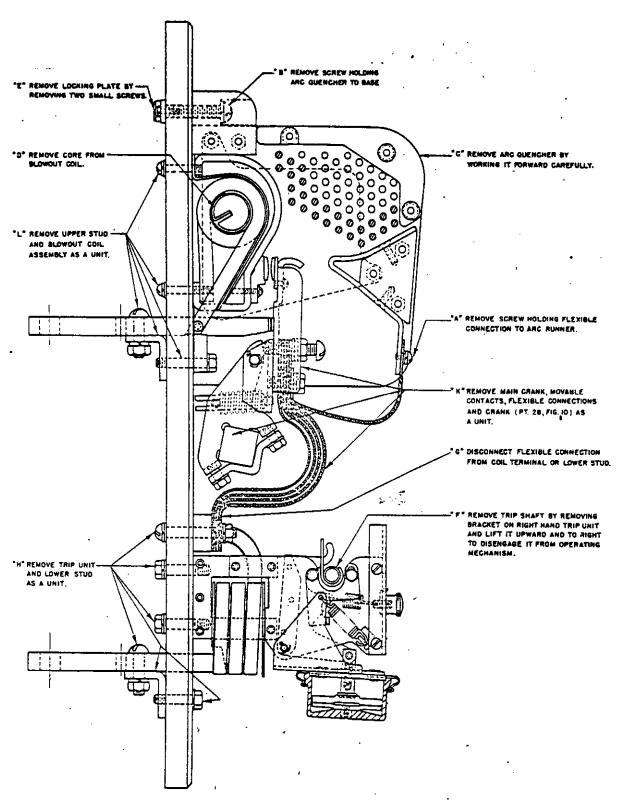
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[&]quot;I" (SEE FIG. 10) REMOVE COMPRESSION SPRING (PT. 25) BY PRESSING SPRING GUIDE (PT. 24) TO REAR AND REMOVE IT FROM CAM (PT. 22) AND CRANK (PT. 27)
REMOVE PIN FROM CRANK.

NOTE: - OTHER DEVICES SHOULD BE REMOVED AS UNITS WITHOUT DISTURBING ADJUSTMENTS OR GALIBRATIONS.

INSTALL THE ABOVE PARTS AND DEVICES ON PERMANENT BASE IN THE REVERSE ORDER.

[&]quot;J" (SEE FIG. 10) REMOVE OPERATING MECHANISM AS A UNIT BY REMOVING SCREWS FROM REAR OF BASE.

INSTALLATION

LOCATION

The AE-1-25 breaker should be installed in a clean, dry place where it is readily accessible for convenient operation, inspection and maintenance. When mounted on a live front switchboard it should preferably be located at the top of the panel. Space of at least 8" should be allowed above arc quenchers if no barriers are provided.

Most breakers are shipped on permanent bases, or panel sections, with or without enclosures, and the mounting consists of simply bolting the bases to the supporting framework or structure.

Silver contacts, described under "Contact Assembly" should be checked as follows before the breaker is put in operation:-

- Wipe off any dust which may have collected on the contact surfaces with a clean cloth.
- 2. Clean the contacts with a good grade of silver polish or very fine sandpaper to remove any dark surface film so that the contacts are clean and bright. If silver polish is used, be careful to remove all polish from the contacts or insulated parts, after cleaning. If sandpaper is used, care must be exercised to maintain line contact.
- 3. Take contact impressions as described under "Contact Assembly" to determine if proper line contact is being maintained. If necessary, improve the contacts as described under "Maintenance".

BREAKER CONNECTIONS

Before connecting current-carrying bus bars or cables or secondary control wiring, every precaution must be taken to be sure that all leads to be connected to the breaker are de-energized.

The connections to the breaker studs should be clean, flat and free from burrs to assure full contact area and firmly clamped or bolted in place to prevent excessive. heating. In enclosed breakers the cables should be clean and of ample size to assure full contact surface when attached by the swivelled clamping screw in the solderless connectors. The connecting bus bars or cables should have adequate current-carrying capacity, otherwise, heat will be conducted from them to the breaker which could not be expected to carry normal current without exceeding the specified temperature rise. Connecting cables or bus bars should be supported so that the breaker stude will not be subjected to unnecessary strains.

DEAD FRONT BREAKERS

Breakers equipped with dead front barriers, Fig. 2, can be installed on framework or elsewhere without removing the barriers.

ENCLOSED BREAKERS

The enclosed breakers, Fig. 3, can easily be installed by first removing the cover and the two top mounting bolts in the breaker base, Fig. 4. Tilt the breaker unit forward to disengage disconnects and for removal. Next, mount the box in the desired location and secure the cables in the solderless connectors in the box, (Fig. 5). Finally, return the removable breaker unit to the box, and replace the two upper mounting bolts and the cover to complete the installation.

WHILE INSTALLING, OR BEFORE REMOVING THE BREAKER, IT IS IMPORTANT THAT IT SHOULD BE IN THE OPEN POSITION.

TEMPORARY BREAKER MOUNTING

It is always preferable to have an air circuit breaker shipped on a permanent base or panel section. Remounting of a breaker by persons not entirely familiar with its detailed construction may result in misalignment or improper adjustment with resultant unsatisfactory operation. Temporary bases will not be supplied when reverse current trip devices are involved.

For those cases where it is found necessary to transfer a breaker from a temporary base to a permanent base or panel, first make sure that the permanent base or panel is properly drilled in accordance with an approved drilling plan furnished by the General Electric Company for the particular breaker. In transferring the breaker, it should not be dismantled any more than is necessary to affect the transfer. Sub-assemblies, such as overcurrent devices, the operating mechanism, etc. should be transferred as units. This will help maintain. adjustments and will minimize the possibility of incorrect assembly. A recommended sequence of procedure for transferring an AE-1-25 air circuit breaker is given in Fig. 6. It is suggested that this procedure be followed in the order in which the operations are alphabetically arranged. Reinstall parts and devices on the permanent breaker base in the reverse order. It is important that the main shaft and crank (Pt. 27, Fig. 10) should move freely in bearings and clear of cam (Pt. 22, Fig. 10) before spring (Pt. 25, Fig. 10) is installed. After the transfer has been completed and the operating mechanism, main and trip shafts are working freely, the alignment of the contacts and operation of all parts should be checked as described under "Operation" and "Contact Assembly".

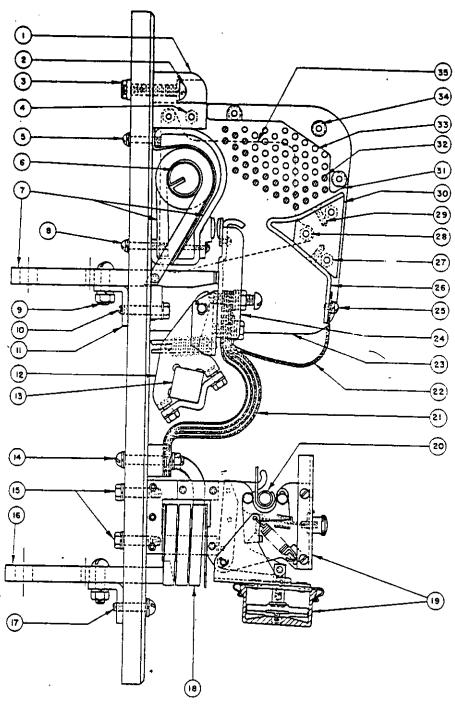
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- L SUPPORT

2. SCREW R.H. (2-18 WITH LOCKWASHER

3. LOGKING PLATE WITH WELDED NUT

4. SCREW R.H. (10-32 X 2 1 WITH LOCKWASHER AND NUT

5. SCREW R.H. (10-32 WITH WASHER AND LOCKWASHER

6. STEEL CORE OF BLOWOUT COIL

7. UPPER STUD AND STATIONARY CONTACT ASSEMBLY (SEE FIG.8)

8. SCREW R.H. (10-32 WITH WASHER AND LOCKWASHER

9. SCREW R.H. (10-20 WITH LOCKWASHER AND NUT

10. SCREW HEX. HO. (10-20 WITH LOCKWASHER

11. STUD BRACKET

12. MOVABLE CONTACT SUPPORT

13. MAIN STAFT

14. SCREW R.H. (10-20 WITH WASHERS, LOCKWASHERS, AND NUT.

15. SCREWS HEX. HO. (10-20 WITH WASHERS AND LOCKWASHER

16. LOWER STUD

17. SCREW ROUND HO. (10-20 WITH LOCKWASHERS)

18. SERIES COIL
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19. DUAL OIL FILM MAGNETIC OVERGURRENT TRIP DEVICE (SEE 20. TRIP SHAFT

21. MAIN FLEXIBLE CONNECTION

22. FLEXIBLE CONNECTION

23. SIDE PLATE OF ARG QUENCHER

24. MOVABLE CONTAGT ASSEMBLY (SEE FIG.8)

25. SCREW RN. ©10-32 WITH WASHER AND LOCKWASHER

26. FRONT ARG RUNNER

27. SCREW RN. ©10-32 X 2½ WITH LOCKWASHER AND NUTS

28. SCREW F.N. ©10-32 X 2½

30. INSULATION BLOCK

31. BAFFLES

32. PINS. HIGH MELTING POINT

33. PINS. COPPER

34. SCREWS, RN. ©10-32 X Z 26 WITH LOCKWASHER AND NUTS

35. POLE PIECE PLATES

TO After the breaker has been installed, slowly operate it manually several times (as described below) and observe whether the contacts line up properly and make sure that all parts move freely in a proper marmer without binding or excessive friction. See that the breaker latches securely and trips freely. If the breaker is equipped with un undervoltage device the breaker cannot be latched unless normal potential is applied to its coil, or the plunger is forced into the coil.

Manually operated AE-1-25 breakers, covered in these instructions, are closed by first turning the operating handle in the counter-clockwise direction from the normal position of "handle down" to a position of "handle up" to reset the operating mechanism latch, and then turning the handle in a clockwise direction to position of "handle down" to close the breaker (as described under "Operating Hechanism"). DO NOT ATTEMPT TO OPEN THE BREAKEA BY COUNTER-CLOCKVISE ROTA-TION OF THE OPERATING HANDLE. The breaker is opened by pushing on the trip button to release the trip latch. The handle remains in the "down" position after tripping.

Electrically operated AE-1-25 breakers, covered in these instructions, may be closed manually by inserting a maintenance closing handle between the armature and the left side frame and under the pin which connects the armature to the operating mechanism, (as described under "Solenoid Operating Mechanism). The breaker is likewise opened by pushing on the trip button to release the trip latch, and not by the maintenance closing handle.

The electrically operated breaker is automatically reset by the falling of the armature when the breaker is tripped; but not if the maintenance closing handle is in place. Therefore, if the breaker has been closed by the maintenance closing handle, be sure to remove it before attempting to trip the breaker.

After checking the operation manually, as above, an electrically-operated breaker should be operated electrically at rated voltage a for times to make sure that all control circuits are properly connected and the closing solenoid, closing relay and other control attachments are functioning properly. Bear in mind that the solenoid is rated for intermittent. service. Reasonable care should be exercised when testing to avoid overheating of the solenoid by repeated operations.

MAINTENANCE

exist. An inspection of the contacts are quenchers should always be made after it 11s known that the breaker has opened a severe short circuit. If the breaker remains open or closed for a long pariod of time, it is recommended that arrangements be made to open and close it several times in succession, clean and lubricate, where necessary, to keep the contacts and moving parts in good working condition.

Before inspecting or repairing, make sure that the breaker and accessories are disconnected from all electric power, both primary and control voltages.

If overheating, not caused by overcurrent, is observed, look for loose connections, or damaged contacts or flexible connections.

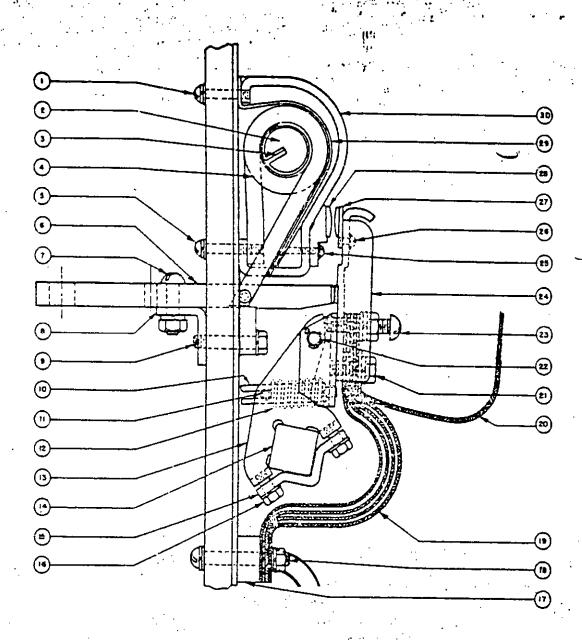
Periodic maintenance of contacts should include the following:

- 1. Wipe off dust and clean the contacts as described under "Installation".
- 2. Take contact impressions, as described under "Contact Assembly", and improve the contacts if necessary. Remove high or rough spots with a fine clean file or very fine sandpaper. Do not use emery or crocus cloth. Small pittings need not be remove: if 75% of line contact can be obtained.

In general, the breaker mechanism requires very little lubrication which should be applied sparingly. Any excess amount o oil on the breaker parts is apt to collec dust and dirt and is to be avoided. A gen eral recommendation for lubrication of 2 air circuit breaker mechanism is to occasion ally use a few drops of a good grade of ligh machine oil at bearing points and wipe of any excess with a clean cloth. Latch sur faces should be kept smooth and clean wit crocus cloth. They should be lightly grease and the excess removed with a clean cloth.

If the breaker is equipped with an type of oil-film time delay trip devices make sure that, when the breaker is install ed, the oil pots of these devices are thor oughly cleaned and filled with oil to th proper level as marked on the pots. It-i important that these oil nots be kept clea and properly filled with fresh oil to th proper level at regular inspection period at least every six months, and more frequent ly if_service is severe. A small can of oi for use in these pots is furnished with eac a breaker. readditional oil, per General Electri Company specifications D6B7Al, can be ob tained from the factory. When cleaning the .oil.pots, use kerosene or naptha only, an ewipe dry with a clean cloth - Other cleaning recommended at least once a year, or more fluids may act as a solvent of the materia

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- II. SCREW RIL # HE WITH LOCKWASHER
- 2 SOME OF BLOWOUT COIL
- I INSULATION
- 4 BLOWOUT COIL
- S. SCREW RH. @ 10-32 WITH WASHER AND LOCKWASHER
- & UPPER STUD AND SHVER CONTACT
 7. SCREW R H. 4- EO WITH LOCKWASHER AND NUT
- B. SCREW HEX. HD 4-20 WITH LOCKWASHER
- IG SPRING GUIDE

- II. PIN IN CONTACT SUPPORT
- IZ COMPRESSION SPRING
- IS CONTACT SUPPORT
- I4 MAIN SHAFT
- IS CLAMP
- IE SCREW HEX. HD. 4-20 X 2 WITH LOCK-WASHER
- IT. TERMINAL OF SERIES COL OR LOWER STUD
- IL SCREW R.H. 1-20 WITH WASHER, LOCK-.. WASHER AND HUT!
- 19 MAIN PLEXIBLE CONNECTION 20 FLEXIBLE CONNECTION
- SCREW HEX.HD, \$ #X } WITH WASHER
- 22. PIN IN CONTACT SUPPORT AND COTTER PINS ES. ADJUSTING SCHOW R.H. 1 10X 14 WITH
- WASHER, LOCKMASHER AND KUT 24. MOVAPLE CONTACT AND SILVER CONTACT
- 25. SCREW R.H. & 6-40 X WITH LOCKMAHER ZE. SCREW RLH. # 6-40X WITH LOCKWASHER
- 27. MOVABLE ARCHIG CONTACT
- 28. STATIONARY ARCING CONTACT
- 29 INSULATION
- 30. STATIONARY ARC RUNNER, WELDED TO FEE

FIG. 8 CONTACT ASSEMBLY of different degrees of conductivity to short circuit insulation strips or barriers between surfaces of different potential on breaker parts or attachments. Even oil on such insulation surfaces may accumulate dirt to allow leakage of current.

Further discussion of maintenance inspection and trouble-shooting will be found in "How to Maintain Air Circuit Breakers", GET-1165.

DESCRIPTION OF COMPONENTS' AND ATTACHMENTS

Although, under this heading, the adjustable features of the air circuit breaker and its attachments are given, it should be understood that the breaker has already been adjusted, tested and inspected at the factory in accordance with the information given herein. However, it is possible that unusually rough handling, transportation, and operating conditions may have resulted in some loosening or disturbance of the equipment to warrant re-checking and, in some cases, readjustment may be necessary.

CONTACT ASSEMBLY

. 6

Current is carried through the breaker by solid copper studs, stationary and movable contacts, and flexible connections, as shown in detail in Fig. 8, (see also Fig. 7). The stationary contact assembly consists of an upper stud (Pt. 6) with a brazed silver contact, blowout coil (Pt. 4) and stationary arc runner (Pt. 30), riveted and silver soldered together as one unit and attached to the mounting base by bracket (Pt. 8) and screws (Pts. l and 5). A sheet of insulation (Pt. 29) separates the blowout coil and the arcing horn. The main silver contact strip is silver soldered to the front of the upper stud. The removable stationary arcing contact (Pt. 28) with silver alloy contacts is attached to arc runner by screws (Pt. 25).

The movable contact assembly consists of a movable contact (Pt. 24) pivoted to a contact support (Pt. 13) by pin (Pt. 22) and the contact support is rigidly attached to the square main shaft (Pt. 14) by clamp (Pt. The square shaft is covered throughout its length with heavy insulating material and extends through the movable contact assembly of each pole and is connected to the poperating mechanism by crank (Pt. 27 Fig. 10)... A main silver contact strip is silver soldered to the movable contact. The removable arcing contact (Pt. 27), with silver alloy inserts, is attached to it by screws (Pt. 26). The flexible connection (Pt. 19) is attached to the movable contact by screws (Pt. 21 and 23) and to the upper end of the series coil, or lower stud, by screw (Pt. 18). Compression spring, (Pt. 12), mounted over guide (Pt. 10) and backed up by pin (Pt. 11) in the contact support, causes the movable contact to revolve about pin (Pt. 22) in the contact support to maintain pressure between the main contacts, when the breaker is closed.

In closing, the arcing contacts close before the main contacts close, and, as the contact support (Pt. 13) is drawn further to the rear, the movable contact (Pt. 24) revolves over the main contacts as a fulcrum to draw the arcing contacts apart. Screw (Pt. 23) must be adjusted to cause a gap of .020 to .040 between the arcing contacts when the breaker is latched closed.

Compression spring (Pt. 12) should be set to require a pull of 19 to 24 pounds, applied at the movable arcing contact, to open the main contacts. The arcing contacts should be separated by 3/4" to 1" when the breaker is open. When the arcing contacts just touch, the main contacts should be between 1/16 to 3/16" apart.

As the breaker opens, the arcing contacts close again and remain closed until after the main contacts open. Thus, when the main contacts open the breaker current is shunted to the arcing contacts to prevent burning of the silver contacts. When the movable arcing contact (Pt. 27) passes under the front arc runner (Pt. 26 Fig. 7) of the arc quencher, the breaker current is again shunted over flexible connection (Pt. 20) to the arc runner, and the arc is transferred to the front and rear arc runners and among the pins of the arc quencher. A magnetic field is set up by the shunted current through the blowout coil (Pt. 4) which quickly opens the circuit as described under "Arc Quenchers".

The breaker is equipped with fine silver high pressure line type main contacts, silver soldered to the upper stud (Pt. 0) and the movable contact (Pt. 24). The surfaces of these contacts have been coated with wax at the factory to prevent the formation of surface film. The wax will not interfere with operation as it will volatilize at normal operating temperatures of the breaker.

To maintain line contact in the AE-1-25 breaker the silver inserts on the movable contact are machined flat but those on the upper studs are slightly curved. It is important for proper breaker operation that adequate line contact be maintained which can be checked as follows: -- Hold between the contacts a piece of thin carbon paper with tissue paper on the carbon side. Close and open the breaker and examine the impression on the paper. Good contact is indicated if a well defined impression shows for 75% or more of the length of the contact. Good contact is also indicated if a .002" feeler gauge cannot be inserted between the contacts for more than 25% of the length of the contact. Should poor contact be found, it will be necessary to improve the contacts as described under "Maintenance". The curved surface should be maintained on the stationary contact so that the line contact will not be too broad.

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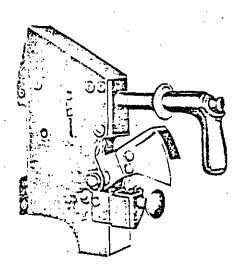
ARC QUENCHERS AND BARRIERS

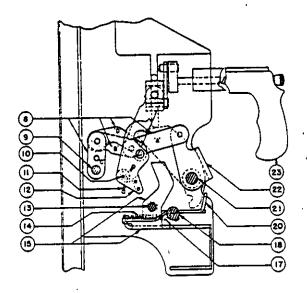
An are quencher is provided for each pole of AE-1-25 breakers to quickly extinguish the arc after the contacts open. Each arc quencher, Fig. 7, consists of a large number of small solid pins (Pts. 32 and 33) supported between molded compound side plates (Pt. 23) which are placed vertically on both sides of each set of contacts. The pins are copper except those in the two lower rows which are of a metal that has a higher melting point than copper. Baffles (Pt. 31) of molded compound are placed between the side plates above and in front of the pins. An arc runner (Pt. 26) is mounted on an insulation block (Pt. 30) between the side plates and in front of the pins. To this runner is connected a flexible shunt connection (Pt. 22) after the arc quencher is in place. Pole piece plates (Pt. 35) are placed on the outside of the side plates and act with the blowout coil with a slotted steel core (Pt. 6) of the stationary contact to provide a magnetic path to blow the arc upwards on the arc runners and among the pins and baffles when the breaker current is shunted from the contacts as described under "Contact Assembly". The steel core, enclosed in insulation, is inserted in the coil when the arc quencher is installed. As the arc travels up the arc runners and through the pins and baffles it is lengthened and cooled which quickly opens the circuit. Each arc quencher is attached to the mounting base by a screw (Pt. 2) which passes through a mounting support (Pt. 1) in the upper part of the arc quencher and which engages a locking plate (Pt. 3) mounted on the rear of the mounting base.

For dead front and enclosed AE-1-25 breakers a box type barrier of molded compound is provided to fit over the top, sides and front of all arc quenchers to confine the arcs. Barriers are provided to isolate each pole unit. The front is attached by nuts and can be removed for inspection of arc quenchers. The barrier rests on a horizontal strip above the arc quenchers and is attached to the circuit breaker base by two long bolts with front nuts shown in Fig. 2.

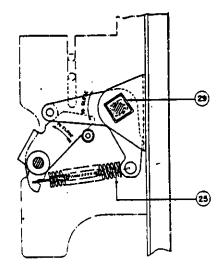
MANUAL OPERATING MECHANISM

The manually operated mechanism of the AE-1-25 breaker is operated by revolving a pistol grip handle (Pt. 23) located at the front of the mechanism, as shown in Pig. 10. The normal position of the handle is "down" and in order to close the manually operated breaker, it must be turned counter-clockwise approximately 180° to the "reset" position which resets the latch (Pt. 12), and then must be turned clockwise to the "down" position, to close the breaker. The mechanism is tripped by pushing on a trip button in the bottom front part of the side frame of the mechanism, or by any tripping device which revolves the trip shaft (Pt. 18) in a counter-clockwise direction (looking from









(MEW FROM RIGHT SIDE)

FIG. IO A

TRIPPED POSITION

loft) to release the latch (Pt. 12). When tripped manually or by any tripping device, the handle remains in the "down" position. Therefore, to reclose the breaker, the handle must first be turned counter-clockwise to he "reset" position and then clockwise to he "down" position as described above.

The operating mechanism, Fig. 10, of the manually operated breaker consists of a group of toggles, links, levers and a latch attached to the frame by fixed pins (Pt. 9, 10, 13 and 21). The insulation covered main shaft (Pt. 29) the trip shaft (Pt. 18) and the handle shaft also have fixed bearings in the frame. All parts move otherwise on floating pins. The mechanism operates a cam assembly (Pt. 22) to close the breaker and places springs (Pt. 25) of the mechanism and springs (Pt. 12, Fig. 8) of the movable contact assembly under compression. Tripping, by any means, releases the latch (Pt. 12) to allow these springs to extend which supplies the power to open the breaker and hold the contacts apart after tripping.

A torsion spring (Pt. 11) around pin (Pt. 10) applies force to the latch (Pt. 12) in the clockwise direction to reset the latch. The spring (Pt. 14) jointly holds prop (Pt. 15) in the vertical position and trip arm (Pt. 20) in the normal position.

In a cycle of manual operation, the mechanism parts take three positions as follows:-

TRIPPED POSITION - In the tripped position Fig. 10A, the latch (Pt. 12) of the togtle mechanism is in the vertical position and is free of the latch plate (Pt. 17) which is attached to the trip shaft (Pt. 18). The handle is down. Other parts assume positions as shown.

RESET POSITION - When the manual handle (Pt. 23) is turned counter-clockwise to the "reset" position with handle up, Fig. 10B, the eccentric (Pt. 1) on the handle shaft lowers link (Pt. 2), block (Pt. 4) and a pair of closing links (Pt. 6), collapsing toggle links (Pt. 8A and 8B) causing the latch (Pt. 12) to revolve about its fixed pin (Pt. 10) in frame and engage the latch plate (Pt. 17).

CLOSED POSITION - When the manual handle (Pt. 23) is turned clockwise from the "reset" position to the "closed" or "down" position Fig. 10-C, the closing links are raised to the vertical position, extending toggle links (Pt. 8A and 8B) which forces the cam (Pt. 22) forward, because the pin in the rear end of toggle link (Pt. 8D) is held fixed by latch (Pt. 12) which is engaged on latch plate (Pt. 17). The cam raises the operating crank (Pt. 27) which turns the main shaft (Pt. 29) to the closed position to close the contacts. At the same time a torsion spring around pin (Pt. 13) draws prop (Pt. 15) under closing links (Pt. 6) to prewent opening of the breaker by counterclockwise rotation of the manual handle.

The type AE-1-25 breaker is trip free because the toggle links (Pt. SA and SB) cannot be extended to move the cam (Pt. 22) forward as long as the trip shaft (Pt. 18) is held in the tripped position by any device. This prevents the latch (Pt. 12) from being held by the latch plate (Pt. 17) as shown in Fig. 10B, and even if an attempt is made to close the breaker, the latch simply returns to the tripped position of Fig. 10A, without moving the cam (Pt. 22) forward.

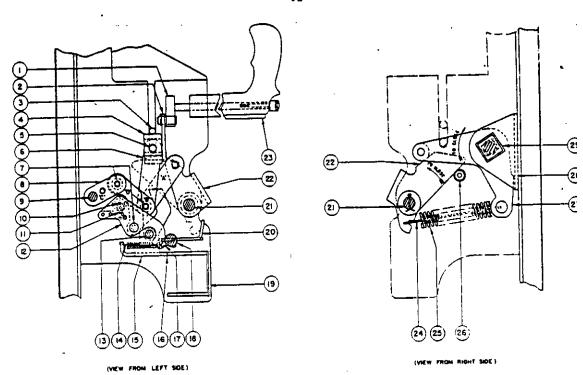


FIG. 10 B RESET POSITION

L ECCENTRIC SHAFT 2. LINK 3. GLIDE WELDED TO BLOCK 4. BLOCK 1. PM 4. CLOSING LINKS 7. RIVETED OVER PM 1. TOGGLE LINKS A.B.C. B.D. 2. PM IN FRAME D. PM IN FRAME	II. TORSKON SPRING 12 LATCH 13 PM IN FRAME 14 SPRING 15 PROP 16 STOP SURFACE FOR PROP 17 LATCH PLATE 18 TRIP SHAFT 19 FRAME 20 TRIP ARM	21. PM: M FRAME 22. CAM 23. MAMIAL, CLOSING HANGLE 24. GUIGE 25. OUTER AND INNER COMPRESSION SPRINGS. 26. CAM STOP 27. OPERATING CRAMK 28. BRACKET 29. MAIN SMAFT
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POSITIONS OF OPERATING MECHANISM (A,B,&C)

Adjustments are made by cams as shown in Fig. 11. To adjust the engagement between latch (Pt. 2) and latch plate (Pt. 5), slowly move the trip arm (Pt. 7) by hand, with the breaker closed, and measure the travel A, of the front end of the arm from the point of rest to the point of trip, which should be between 1/8 and 3/16. Adjustment can be made by loosening the screw (Pt. 9) and turning the eccentric stop (Pt. 8), on the left side of the operating mechanism frame, which bears against the buffer spring (Pt. 10) attached to the left end of the trip shaft (Pt. 6). After adjusting the eccentric be sure to tighten the screw.

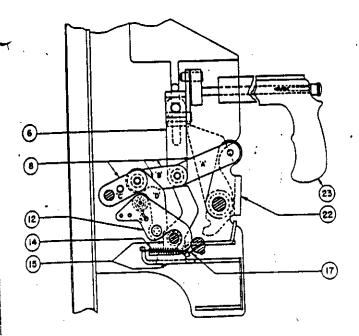
The latch clearance adjustment is obtained by turning eccentric cam (Pt. 4) by screw-driver after loosening nut (Pt. 3). Although the cam is on the inside of the operating mechanism frame, a threaded shank with a screw-driver slot extends through the frame. A clearance "B" of approximately 1/64" should be allowed between the latch (Pt. 2) and the cam when the latch rests against the latch plate (Pt. 5). If the clearance is too great, the latch receives

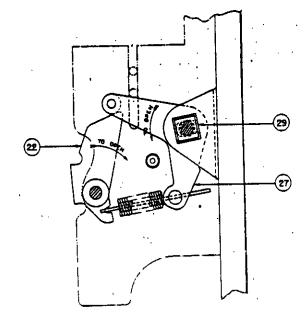
too great shock, particularly from t ing of the solenoid, and if the clea too small, the latch will not reset. to tighten the lock nut securely af justment.

In replacing the latch plate (F is important that the point of contac latch plate should be on the upper shown in the insert of Fig. 11, and the lower side.

SOLENOID OPERATED MECHANISM

The electrically operated mecha the type AE-1-25 breaker is the sammanual operation except that the forparts of Fig. 10, manual handle (Feccentric shaft (Pt. 1), link (Pt. 2 (Pt. 3) and block (Pt. 4) are replasolenoid of Fig. 13 and a closing Fig. 14. In solenoid operation the of the latch is automatic, in that the of armature (Pt. 4, Fig. 13) causes lapse of toggle links (Pts. 10A and 10), which duplicates the resetting manually operated mechanism descrifig. 10B.

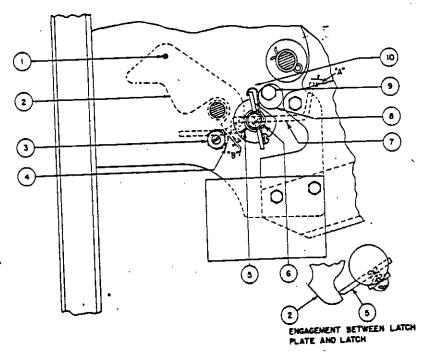




(VIEW FROM LEFT SIDE)

(VIEW FROM RIGHT SIDE)

FIG. IO C CLOSED POSITION (OF OPERATING MECHANISM)



- I. PM IN FRAME

- S.LATCH PLATE

- 6. TRIP SHAFT
- 7. TRIP ARM
- 8. ECCENTRIC
- 4. ECCENTRIC WITH THREADED SHANK 9. SCREW HEX. HO. 10-32 X TO WITH LOCKWASHER
 - 10. BUFFER SPRING

FIG. 11

ADJUSTMENT ECCENTRICS FOR TRIP ARM AND LATCH

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יונ ٦r g , Le a 元 財 場 二 ・ 10 Manual closing of the solenoid operated breaker is shown in Fig. 13 by inserting a maintenance closing handle (Pt. 7) through the front of the mechanism under pin (Pt. 5) between the armature (Pt. 4) and the left side frame (Pt. 2) and resting it on pin (Pt. 6) as a fulcrum. Pushdown on the handle and be sure that the armature is lifted until the breaker is latched closed.

The breaker is likewise tripped by pushing on the trip button to release the trip latch, and not by the maintenance closing handle. In closing the breaker with the maintenance closing handle, it is important to remove it before tripping, as the breaker will have to be reset if the handle is still under the armature.

CLOSING RELAY

An electrically operated AE-1-25 breaker is equipped with a closing relay, Fig. 14, which operates to control the solenoid closing coil current so that the closing switch contacts will not be called upon to break the main closing coil current. This relay is attached to the mounting panel directly below the operating mechanism. No adjustments are required except to keep the contacts clean.

The coil (Pt. 2) is mounted in the magnet (Pt. 1), which is screwed to a separate mounting base (Pt. 11). The coil is held in place

by two brass guides (Pt. 3) between armature (Pt. 4) is free to move. ends of the guides are clamped over ti and against the coil to keep it fi place, and the upper ends are fasten magnet by self-tapping screws (Pt. 1 the coil is energized by the closin operating switch, Fig. 16, or a remoti relay contacts or other devices, the is drawn up into the coil. It carr it a movable contact strip (Pt. 7 bridges the stationary contact block: to energize the breaker closing coil control power source and close the As soon as the coil is de-energiz armature falls by its own weight and (breaker closing circuit at the mova tact strip.

ROTARY TYPE AUXILIARY SWITCH

The rotary type auxiliary swit 15, is the SB-1 type and is used electrically operated AE-1-25 brea on manually operated breakers when functions are required. It is giplaced on the mounting panel above the ing mechanism and connected by craniand link (Pt. 9) to the operating c: 27, Fig. 10) of the breaker main should be successful to switches are determined by the functions desired and the character circuits to be controlled such as i lamps, control circuits, bell alarm locking of breakers, etc.

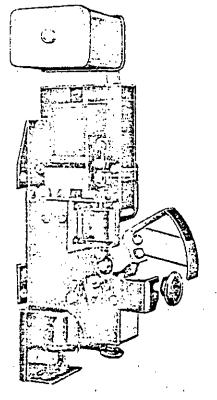


FIG. 12 ELECTRICALLY OPERATED MECHANISM.

n a plane at right angles to the shaft. A stationary contact support (Pt. 4) carries the stationary contacts of all stuges and is attached to the front frame and the rear barrier by two round head screws. Two bolts pass through the molded barriers and through the front end frame (Pt. 7). When the shaft is rotated the cam of each stage opens or closes both movable contacts simultaneously. In the auxiliary switch for the AE-1-25 breaker the two stationary contacts are insulated from each other in order that both switches of each stage may be connected in series for one circuit with two breaks as in Stage 1, ormay be used for two separate circuits with one break in each circuit, as in Stage 2, as shown in wiring diagrams, Fig. 39 and 40. The cam bushing fits over the square shaft (Pt. 10) and has 24 external teeth and the cam (Pt. 7) with 24 corresponding internal teeth fits over the bushing to allow steps of 150 placement with reference to its setting on the shaft. The proper placement of the cam on the bushing and the bushing on the shaft is important for proper operation of the breaker. There is an index mark on the bushing and reference marks on the cam for this purpose.

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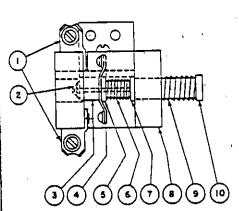
The contacts of any stage may be changed from "a" to "b", or any intermediate position required, by a change in breaker operation by changing the position of the cam with reference to the shaft. If a change of 900 is required, the cam and bushing should be re-

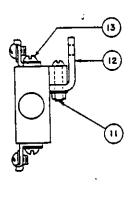
> FIG. 16 OPERATING SWITCH

moved together and replaced on the square shaft in the proper position. If the change is 150 or a multiple of 150 the cam will have to be relocated on the bushing. Each reference mark on the cam represents 150 of angular placement.

To make the change in the field, first remove interfering wiring and the stationary contact support (Pt. 4) with all the stationary contacts (Pt. 3) by removing two round head screws. Then remove the two tie bolts which hold the molded barriers (Pt. 1) to the front end frame (Pt. 7). Now remove the rear molded barrier with the two movable contacts of the rear stage, which will leave the cam and bushing of the rear stage exposed. Continue removing molded barriers, cams and bushings until the cam to be changed is exposed. In removing cams and bushings be particularly careful to make an accurate sketch showing the relation of reference marks on the cams, the index mark on the bushing and the position of the bushing on the shaft, and keep the parts of each stage together. The cam can then be changed to its new position and the auxiliary switch can be reassembled.

At regular inspection periods of the breaker, the auxiliary switch should be examined for burned contacts, and broken shunts on contact fingers. If contacts are slightly pitted or coated with oxide, scrape them gently with a sharp knife or dress with a





- I. CONTACT BRACKETS AND BINDING SCREWS 2. SCREW R.H. 4-40XI WITH WASHERS
- 3 GUIDE
- 4 . MOVEABLE CONTACT STRIP
- 5 INSULATION
- 6 . SPRING
- 7 . WASHER
- 8 . MOLDED BASE
- 9 . SPRING
- IO. OPERATING ROD
- II. SCREW R.H. 8-36 X 3 WITH NUT & LOCKWASHER
- 12, MOUNTING BRACKET
- 13. SCREW R.H. TO-32 X WITH LOCKWASHER

fine file. If the moving contact is burned or has a broken shunt, the entire contact finger assembly should be replaced. If a stationary contact is burned or damaged the complete stationary contact support and contacts should be replaced.

OPERATING SWITCH

The operating switch, Fig. 16, which energizes the closing relay, Fig. 14, of the solenoid operated breaker, is mounted on the front of the solenoid magnet. It requires no attention other than keeping the contacts clean.

The switch consists of a molded base which supports an operating rod (Pt. 10) on which rides a movable bridging contact strip (Pt. 4) and also contact brackets (Pt. 1) which carry the stationary contacts and binding screws. A compression spring (Pt. 9) normally holds rod and contact strip in the open position. Contact spring (Pt. 6) exerts pressure of the contact strip against the stationary contacts when in the closed position.

CUT-OFF DEVICE

The purpose of the cut-off devices, Fig. 17, for the AE-1-25 breaker is to deenergize the breaker closing coil (Pt. 3, Fig. 13) as soon as its armature has been lifted sufficiently to latch the breaker closed, to prevent damage to the closing coil should the operating switch, Fig. 16, be held in the closed position too long. This device is necessary when maintained contact control switches are used, as shown in Wiring Diagrams, Fig. 38 and 40.

The device consists of a two circuit switch and a holding coil mounted vertically on flanges of bracket (Pt. 2) which is attached to the left side frame (Pt. 3) of the operating mechanism. The switch is operated by a flat spring (Pt. 5) which is pivoted on pin (Pt. 4) mounted in this bracket. This spring is lifted by pin (Pt. 6) which replaces pin (Pt. 5, Fig. 13) through the armature of the breaker closing solenoid. When the closing solenoid is energized the pin is lifted and the flat spring bears against washer and cotter pin (Pt. 12) in pin (Pt. 13) of armature (Pt. 8). This pin bears against operating rod (Pt. 15) of the switch and opens the normally closed contacts which de-energizes the closing relay Fig. 14, and therefore, opens the closing solenoid circuit. At the same time the normally open contacts are closed which closes the circuit of holding coil (Pt. 11) to seal the contact in this position as long as the operating switch Fig. lo is held in the closed positions. This sealing-in also prevents pumping should the breaker fail to be latched. It is important that this device should not open too soon in the closing stroke of the energize the closing coil before the breaklis latched closed. See also Wiring Diagram Pig. 40.

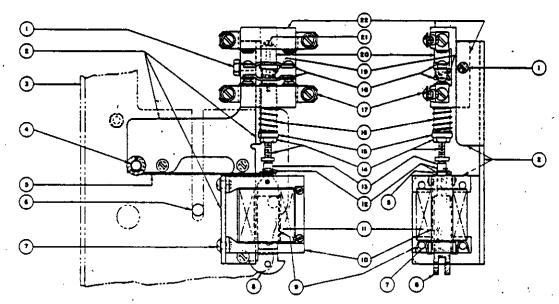
The contact brackets (Pt. 17), with stationary contacts and binding screws, ar mounted on a molded base (Pt. 22). The operating rod (Pt. 15) passes through the lower part of the base, and a guide (Pt. 20), at tached to the upper end of the operating roby screw (Pt. 21), passes through the upper part of the molded base. The movable contact strips (Pt. 18) move over the square section of the guide and are separated a contact spring (Pt. 19) which also maintain adequare pressure against the contact Spring (Pt. 16) normally holds the operation of the lowered position which will clothe normally closed contacts in order that the closing solenoid shall be energized a soon as the closing switch is closed.

DUAL MAGNETIC OVERCURRENT TRIP DEVICE (oi Film Type)

This device, Fig. 18, automatically trithe breaker under two distinct conditions overload; first, with inverse time delay fovercurrents in excess of calibration settiand less than ten times rated current; a second, with instantaneous tripping for interupting overloads exceeding ten times rateurrent.

To accomplish inverse time tripping t current in the series coil (Pt. 9) sets up magnetic circuit which tends to pick up arm ture (Pt. 1) pivoted on pin (Pt. 13) in fre (Pt. 12) and operate trip finger (Pt. 2 and turn the trip shaft counter-clockwi (looking from the left). The armature (Pt. is restrained by a calibration spring (Pt. : held under tension between the armature a sembly and the calibration index (Pt. 23 and also by a thin oil film between upp disc (Pt. 17), which is pivoted to the arm ture assembly, and the lower disc (Pt.] attached to the bottom of oil cup (Pt.] which holds the oil in which both discs : immersed. For currents below the calib: tion setting, the calibration spring pr vents the armature from picking up and force is exerted to separate the discs in oil pot. For currents in excess of the ca bration setting the magnetic pull on the ar ture exceeds the pull on the calibrat: spring (Pt. 21) and the excess force tends pull the two flat disc surfaces (Pt. 16 17) apart by rupturing the oil film betw them. Once this oil film is ruptured, armature picks up and trips the breaker. time required to rupture the oil film var inversely with the force applied and hen inversely with the current through the bre er. Thus, if the overcurrent falls be the calibration setting before the oil f is ruptured the breaker will not trip.

For instantaneous tripping for curr in excess of ten times the breaker rat



- I . SCREW R.H. # 1-34 X 3 WITH NUT AND LOCKWARHER
- 2. FLANGED GRACKET
- 3.FRAME OF OPERATING MECHANISM 4.PIN AND COTTER PIN
- S.PLAT SPRING

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- 6.PIN (REPLACING PM PT 8 FIG.R) 7. SCREWS R.H. 8-36 X WITH LOCKWASHERS
- S. ARMATURE
- SOIUS SAARS .
- IO. MAGNET
- II. COIL
- IZ WASHER AND COTTER PIN

- IS, PIN IN ARMATURE
- 14. SCREW *10-32 WITH LOCKNUT
- IS. OPERATING ROD
- IG, SPRING 17, CONTACT BRACKETS THTIN BING
- IS, MOVEABLE CONTACT STRIPS
- IN CONTACT SPRING
- 20 60:05
- 21. SCHEW R H #4-40X1 WITH LOGRUMSHERS
- 22. MOLDED BASE OF SWITCH

FiG. 17

CUT-OFF DEVICE

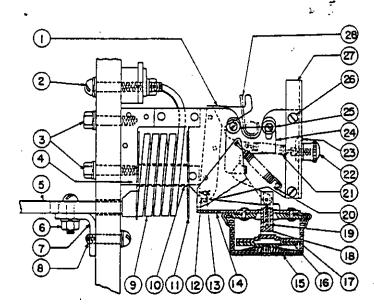


FIG. 18 DUAL MAGNETIC OVERCURRENT TRIP DEVICE. (OIL FILM TYPE)

- SCRIP WELL HULL'S SIL NOW MARKET LOWER STUD (WELDED TO COLL)
 SORTE HILL'S OF HE MARKET LOWER STUD SEACHT
 LOWER STUD SEACHT
 SCRIP RE 1-20 AND MASSIFEE
 SCRIP RE 1-20 AND MASSIFEE
 SCRIP STUD SEACHT
 LOWER SEACHT
 LOWER STUD SEACHT
 LOWER SEACHT
 LOWER STUD SEACHT
 LOWER STUD SEACHT
 LOWER SEACHT
 LOWER STUD SEACHT
 LOWER SEACH

- PRI & COPTERS
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 OIL POT

- IE. LOWER DISC 17. LAPER EISC 18. SHAME 18. SHAME 20. INSTANTANE 21. GALIBRATIO 22. GALIBRATIO

the armature is further restrained by a pair of heavier instantaneous trip springs (Pt. 20), one on each side of the device, attached at the lower front end to the fixed frame (Pt. 12) and at the upper rear end to the cover and support (Pt. 14). This cover is pivoted on pin (Pt. 13) and supports the oil pots. Thus, if overcurrent demands immediate tripping, the heavier pull on the upper disc lifts the complete oil pot assembly, as the springs yield, without waiting for the rupture of the oil film, allowing the armature to pick up and trip the breaker immediately.

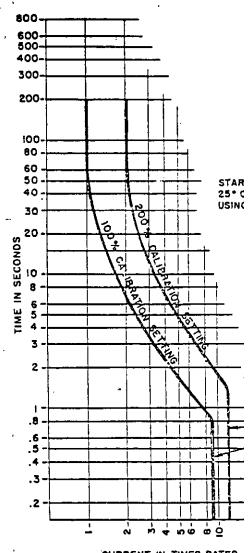
Calibration settings for 100, 125, 150, 175, and 200 per cent of breaker normal current rating are marked in amperes on the calibration plate (Pt. 27). For general feeder applications, the calibration setting should not be less than 125 per cent of actual load being carried by the breaker.

An adjustment is provided for varying the amount of time delay obtained. This is accomplished by turning the oil pot (Pt. 15) to different marked time delay settings, which increases or decreases the area of disc surfaces separated by oil film. The disc surfaces have part of their contact area cut away in the form of a wide band parallel to the diameter of the disc surfaces. The smaller the contact area between discs, the shorter will be the time delay obtained.

The armature air gap is adjusted at the factory by an adjustable stop (Pt. 24) which is pivoted to the frame (Pt. 12) by screw (Pt. 25) in the rear end and adjusted by a similar screw through a slot in the front end. This stop registers with the pivoted cover and support (Pt. 14) which carries the oil pot. By raising or lowering the oil pot, the armature air gap is changed because shank (Pt. 18) is pivoted to both the armature assembly and to the upper disc (Pt. 17). The air gap should not be changed unless means are available for the recalibration of the complete device.

To check the adjustment of this device for positive tripping, pick up the armature manually; the breaker should trip with approximately 1/32° gap between the magnet and the armature. To obtain this adjustment, bend the trip finger (Pt. 28) attached to the trip shaft so that the armature will engage the trip finger sooner or later as required.

It is important that the facing surfaces of the discs be clean and smooth, otherwise the calibration will be affected. If these surfaces are damaged or affected in any way they should be relapped or made smooth by rubbing them over crocus cloth backed up by a smooth, flat surface. It is of utmost importance that the oil in the cup be kept clean and at the proper level. See "Mainte-



CURRENT IN TIMES RATED

FIG. 19
APPROXIMATE TIME-CURRENT CHAI
OF DUAL MAGNETIC OVERCURRENT

If a new series coil is req any considerable repair is necess recommended that a complete fact brated dual magnetic overcurrent vice be supplied.

A typical time-current trip for this device is shown in Fig. curve is approximate and consider tion in time delay may be expect ing upon the cleanliness of the (the film, the time allowed for

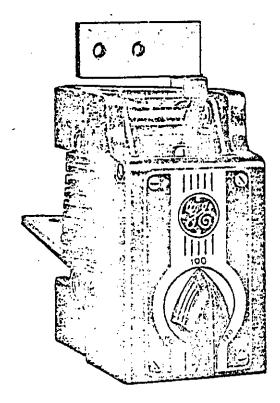


FIG. 20
THERMAL MAGNETIC OVERCURRENT TRIP DEVICE.
(EXTERNAL VIEW)

THERMAL MAGNETIC OVERCURRENT TRIP DEVICE

This device, Fig. 22, also automatically trips the breaker under two distinct conditions of overcurrent, first, with inverse time delay when the current exceeds the value of calibration setting and is less than 12 to 15 times the breaker rating, the inverse time tripping being obtained by the time required to heat and flex a bimetallic strip; and second, instantaneously when the breaker current exceeds 12 to 15 times the normal breaker current.

This device operates on alternating current only, and is principally used for motor protection. The unit is enclosed in a molded frame as shown in Fig. 20.

Current in the series coil (Pt. 5) sets up a magnetic circuit which tends to pick up the armature (Pt. 19) as described below, and operate the trip finger (Pt. 30) on trip shaft. The armature is attached to the lower member of the magnet (Pt. 6) by a spring hinge (Pt. 14) and is restrained by a yoke (Pt. 20) which is pivoted to the center of the armature by pin (Pt. 25) between two flat buffer springs (Pt. 22). The yoke is restrained at the bottom by a latch plate (Pt. 15) and also at the top by two heavy compression short circuit springs (Pt. 1) supported between pin (Pt. 28) in the yoke and the rear frame. Current in the series coil induces current in the short-circuited

ring (Pt. 7), mounted around the lower magnet member, generating heat which is conducted to the bimetallic strip (Pt. 13). This strip is riveted at its rear end to the thermal trip arm (Pt. 9) and held at the front end between the calibrating cam (Pt. 18) and the compression spring (Pt. 16). The thermal trip arm (Pt. 9) is pivoted to the frame on pin (Pt. 8). When sufficient heat has been developed to cause the bimetallic strip (Pt. 13) to bend, with the convex surface downward, the thermal trip arm will tend to revolve about pin (Pt. 8) in a clockwise direction (looking from left) and bear against an adjusting screw (Pt. 12), set in the latch support (Pt. 10), also pivoted on pin (Pt. 8), to cause the latch plate (Pt. 15) to disengage the yoke (Pt. 20) at the lower end. This will allow the armature to be picked up and trip the breaker as the lower end of the yoke moves to the rear over the latch plate (Pt. 15) while the upper end of the yoke is held fixed by the heavy springs (Pt. 1). A torsion spring (Pt. 11) is mounted over pin (Pt. 8) to hold the thermal trip arm (Pt. 9) and latch support (Pt. 10) together against the adjusting screw (Pt. 12). Thus, if the overcurrent falls below the calibration setting before the bimetallic strip is sufficiently bent, the breaker will not be tripped:_

Should the overcurrent exceed 12 to 15 times the breaker rating, the heavier pull on the armature (Pt. 19) will cause the upper

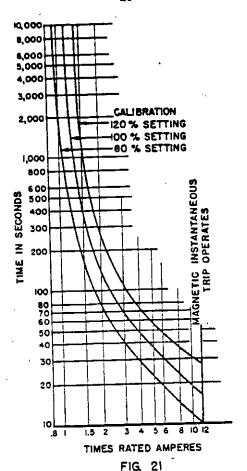
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APPROXIMATE TIME-CURRENT CHARACTERISTIC
OF THERMAL MAGNETIC OVERCURRENT TRIP DEVICE

end of voke (Pt. 20) to compress the heavy short circuit springs (Pt. 1), while the lower end of the voke is held fixed against latch plate (Pt. 15). As these heavy springs yield the armature will pick up and trip the breaker immediately without waiting for release of latch plate (Pt. 15) by the heating of the bimetallic strip as described above.

The lock nut on spring guide (Pt. 2) controls the compression of the short circuit spring (Pt. 1) and is adjusted at the factory to provide instantaneous tripping when the current exceeds approximately 12 to 15 times normal breaker current.

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The adjustable stop screw (Pt. 23) is secured to the armature (Pt. 19) and provides a stop against the front molded frame to control the clearance of 1/16" to 3/32" between the latch surface on the yoke (Pt. 20) and the latch plate (Pt. 15) to insure positive reset. The reset spring (Pt. 26) between adjusting screw (Pt. 27) and the lower end of yoke (Pt. 20), provides the proper tension to the yoke to insure positive resetting after a tripping operation by drawing the lower end of the yoke forward to engage the latch plate (Pt. 15).

strip (Pt. 13) must bend before releasing latch plate (Pt. 15) to trip the breaker.

The calibration adjustment knob (Pt. can be turned to revolve the cam (Pt. 18) indications as marked on the nameplate change the calibration range from 80 to per cent of breaker rating. Revolving the cam raises or lowers the front end of the bimetallic strip against spring (Pt. 16)

To check the adjustment of this dev for positive tripping, pick up the armat manually and the breaker should trip w: approximately 1/32" gap between the armat and the magnet. To obtain this adjustme bend the trip finger (Pt. 30) attached the trip shaft so that the trip arm (Pt. engages this finger sooner or later as quired.

There are available other special cessories that can be attached to the tension of the thermal trip arm (Pt. 9) perform special functions when the bimetal strip (Pt. 13) flexes. These are spec and information concerning them should obtained from the nearest sales office the company.

Typical time-current tripping cur

(27) 0 200 **(19**) (18)

FIG. 22 MAGNETIC OVERCURRENT TRIP DEVICE

L SHORT CHICUIT SPRING 2. SPRING GLEDE AND LOCK NUT

1 TUBULAR SPRING SUIDE AND COTTER

4 MOLDED FRAME

& SERIES COIL

& HAGNET

3 PIDUCTION RING

S. PIN

& THERMAL TRIP ARM

IQLATCH SUPPORT

IL TORSION SPRING

12 ADJUSTING SCREW

IS SIMETALLIG STRIP

14.3PRING HINGE

M. LATCH PLATE

M. SPRING FOR THERMAL TRIP ARM

IT. CALIBRATING KNOS

IE. CALIBRATING GAM, SPRING, AND COTTER

IS ARMATURE

20. YOKE

2L ADJUSTING SCREW AND SPRING

25 FLAT BUFFER SPRING

22 ARMATURE ADJUSTING SCREW AND HUT

Z4 LEATHER BUFFER

ES. YOKE AND ARMATURE PIN

26, RESET SPRING FOR YOKE

27. ADJUSTING SCREW

28, PIN

29 TRIP ARM

30. TRIP FINGER

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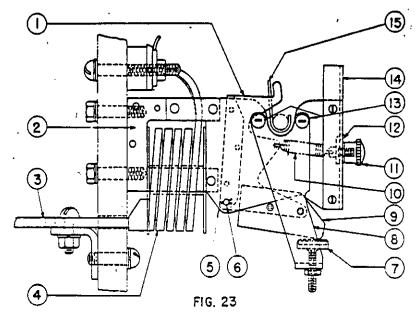
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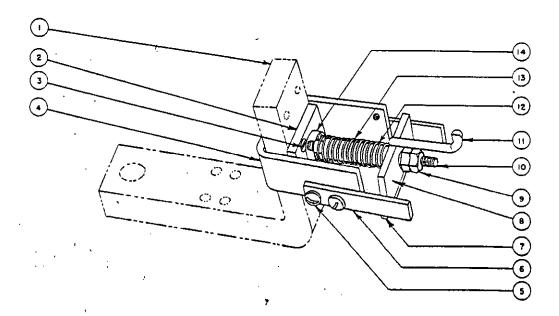
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MAGNETIC INSTANTANEOUS OVERCURRENT TRIP DEVICE

- 1 ARMATURE ASSEMBLY

- 2 MAGNET
 3 LOWER STUD
 4 SERIES COIL
 5 FRAME
- 6. PIN AND COTTER PINS
- 7. STOP AND HEX HUT
- 6. SUPPORT FOR STOP
- 9. STOP PLATE, RIVETED TO ARMATURE ASSEMBLY
- IO, CALIBRATION SPRING
 II, CALIBRATION ADJUSTING KNOB
 IZ. CALIBRATION INDEX
- 13. SCREW R.H. 910-32 X TAND LOCKWASHERS
- 14. CALIBRATION PLATE 15. TRIP FINGER



- 1. LOWER STUD
- 2. BRASS PLATE
- 3. SCREWS , F.H. 10-32 X I
- 4. MAGNET
- 5. SCREWS, R.H. 10-32X TB LOCKWASHER
- 6. BRASS GUIDES
- 7. GUIDE ROD, WELDED TO 8
- 8 . ARMATURE
- 9 , NUTS 1" 20
- IO. BRASS ROD, BRAZED TO 2
- IF, TRIP ARM
- 12. BRASS TUBE
- 13. COMPRESSION SPRING
- 14. BRASS CUP

MAGNETIC INSTANTANEOUS OVERCURRENT TRIP DEVICE

This device, Fig. 23, is magnetically operated to trip the breaker instantaneously by the current through the breaker when this current exceeds the calibration setting. Standard calibration settings for 100, 125, 150, 175 and 200 per cent of breaker normal current rating are marked on the calibration plate. For general applications, the calibration setting used should not be less than 125 per cent of normal load.

This device is similar to the dual magnetic overcurrent trip device without the time delay assembly and support and the heavy instantaneous trip springs. As shown in Fig. 23, the armature has a stop plate or weight (Pt. 9) riveted to it and is pivoted on pin (Pt. 6) in the frame (Pt. 5). It is restrained by the calibration spring (Pt. 10) only. The armature air gap is adjusted by raising or lowering the stop (Pt. 7) in support (Pt. 8) which is attached to the frame (Pt. 5) by screws (Pt. 13).

INSTANTANEOUS SHORT-CIRCUIT TRIP DEVICE

According to NEMA standards, all air circuit breakers shall be inherently automatic for overcurrent tripping. Hence, if the type AE-1-25 breaker is not to be equipped with time delay or instantaneous overcurrent trip device, it will be furnished with an instantaneous short-circuit trip device. For the type AE-1-25 breaker this device is set to operate at 9000 amperes and no provision is made for field adjustment.

The instantaneous short-circuit trip device, Fig. 24, is mounted on the upright portion of the lower stud on the front of the mounting base. It consists of a U-shaped magnet (Pt. 4) attached to the stud (Pt. 1) by flat head screws (Ft. 3) through a brass plate (Pt. 2) to which is brazed a brass rod (Pt. 10). This rod supports the armature assembly (Pt. 8) which includes a guide rod (Pt. 7), the trip arm (Pt. 11) and the brass guide tube (Pt. 12) which slides over the rod (Pt. 10). A compression spring (Pt. 13) slides over the rod (Pt. 10) and fits into a brass cup against the brass plate (Pt. 2) to force the armature (Pt. 8) against the lock nuts (Pt. 9) on the rod. Brass guides (Pt. 6) are attached to the magnet by screws (Pt. 5). Current in the lower stud sets up a magnetic field which ploks up the armature to trip the breaker when trip arm (Pt. 11) engages a trip finger on the trip shaft.

INSTANTANEOUS UNDERVOLTAGE TRIP DEVICE

The function of this device is to trip the breaker when the voltage drops below a predetermined value. As long as a voltage of this value or greater, is impressed on the coil, the armature is held down into the coil and the device has no effect upon closing or tripping of the breaker in any way,

50% of normal, or lower, the magnet is weakened and a strong spring draws the armature out of the coil and causes the breaker to trip. The breaker cannot be reclosed until the necessary voltage returns.

The device, Fig. 25A, is mounted on the front of the mounting base under the breaker shaft and the trip shaft and to the right of the breaker poles. An insulation barrier (Pt. 17) is placed between the mounting strap (Pt. 19) of the device and the mounting base (Pt. 18) and also covers the entire right side of the device. The coil (Pt. 22) is mounted in magnet (Pt. 23) over two brass guides (Pt. 24) between which the armature (Pt. 25) is free to move. The upper ends of the guides are clamped over the magnet and holds the coil in place and the lower ends are fastened to the magnet by screws (Pt. 16). A trip lever (Pt. 9) is pivoted on pin (Pt. 10) in frame (Pt. 13) and is restrained by tension spring (Pt. 12) attached by adjusting screw (Pt. 14) to the same frame which extends forward and is riveted to the sides of the magnet. A trip adjusting screw (Pt. 4) in the trip lever (Pt. 9) bears against the trip arm (Pt. 6) which is attached to the trip shaft (Pt. 5).

Fig. 25A shows the breaker in the open position, with or without potential applied to the coil (Pt. 22). The reset arm (Pt. 1) is in the lowered position against buffer spring (Pt. 2) and the armature (Pt. 25) is forced down into the coil. However, when the breaker is in the closed position, with potential applied to the coil, the reset arm is lifted clear of the buffer spring by the main shaft (Pt. 30) as it revolves clockwise (looking from right) to close the breaker contacts. The breaker cannot be kept closed unless potential is applied to the coil. When the voltage fails, or drops below the predetermined value, the coil is de-energized. This allows spring (Pt. 12) to draw the front end of trip lever (Pt. 9) down and the trip adjusting screw (Pt. 4) bears against the rear end of trip arm (Pt. 6) which causes the trip shaft (Pt. 5) to revolve clockwise to trip the breaker. At the same time the rear end of trip lever (Pt. 9) lifts the armature out of the coil and exerts a hammer blow against the reset adjusting screw (Pt. 29), which is set in the reset link (Pt. 7), causing the latter, together with springs (Pts. 2 and 3) to revolve clockwise about pin (Pt. 28) in the support (Pt. 27). stop link (Pt. 11) is attached by pin (Pt. 8) to the reset link (Pt. 7) and is booked under the trip lever (Pt. 9) to prevent the reset link from springing upward to the vertical position and remaining there. The rear end of the trip lever (Pt. 9) is stopped by pin (Pt. 28).

When voltage is applied to the de-energized coil, the pull of the magnet is not strong enough to draw the armature down into it against the force of spring (Pt. 12) so that a means of resetting must be provided.

When the breaker is open, whether the coil is energized or not, the reset arm (Pt. 1) is against buffer spring (Pt. 2) and the armature is pressed down into the coil, as shown in Fig. 25A, and is therefore in the reset position. When the breaker opens it is automatically reset as follows:- Just as soon as the main shaft (Pt. 30) revolves counter-clockwise to open the breaker contacts, the reset arm (Pt. 1) is forced downwards against buffer spring (Pt. 2) which cause adjusting screw (Pt. 29) to force the armature firmly against the bottom member of magnet (Pt. 23), in the case of alternating current applications, or against set screw (Pt. 15) in direct current application. Then, if potential is applied to the coil, the armature will be held within the coil.

For direct current application, the brass stop screw and locknut (Pt. 15) through the lower member of the magnet are necessary to slightly separate the armature from the magnet to prevent sticking due to residual magnetism and allow tripping.

Adjustments consist first, in direct current application, in setting the stop screw (Pt. 15) so that the bottom of the armature (Pt. 25) is just separated from the magnet (Pt. 23).

Make the following adjustments for both alternating and direct current applications.

With the breaker in the open position and the reset arm (Pt. 1) in the open position, as shown in Fig. 25A, the reset adjusting screw (Pt. 29) should be set to allow between 1/32" to 1/8" between the buffer spring (Pt. 2) and flat spring (Pt. 3) when the reset arm presses against the buffer spring. Then tighten lock nut.

With the breaker in the closed position and the coil de-energized, turn the trip adjusting screw (Pt. 4) in the trip lever (Pt. 9) until the breaker trips, and then continue to turn the screw between 1/2 and 3/4 of a turn more and then tighten the locknut.

The spring (Pt. 12) should be adjusted by adjusting screw (Pt. 14) to prevent dropout of armature (Pt. 25) when the breaker is closed and the coil is energized by voltages above 50% of normal, but to positively trip at 50% of normal or less.

TIME DELAY UNDERVOLTAGE TRIP DEVICE

This device, Fig. 25B, is constructed and operates in a similar manner as in the instantaneous undervoltage trip device with the addition of the oil film time delay attachment and the omission of the reset stop link (Pt. 11). The time delay attachment consists of a disc (Pt. 37) immersed in oil in a dash pot (Pt. 36) which is attached to a cover (Pt. 35) which, in turn, is riveted to the own frame (Pt. 34) and fastened by

7) by plunger assembly (Pt. 33) to delay th tripping of the breaker until the oil film between the lapped surfaces of the disc an the bottom of the dash pot, ruptures. Thus if normal voltage is restored before the oi film ruptures, the breaker will not open.

Pirst adjust, in direct current application, the clearance of the bottom of armatur (Pt. 25) from the magnet by stop screw (Pt 15) as described in instantaneous undervoltage trip device adjustment above.

Make the following adjustments for botalternating and direct current application: Then with the breaker in the closed position and the coil (Pt. 22) de-energized, push the armature (Pt. 25) down into the coil to lover the reset link (Pt. 7) and disc (Pt. 37) Now screw the dash pot cup on the cover (Pt. 35) until the reset link (Pt. 7) begins lift and then turn it another half turn which should make the cup tight against its seal of the seated by about half a turn, then the adjusting screw (Pt. 29) and repeat until this condition is obtained.

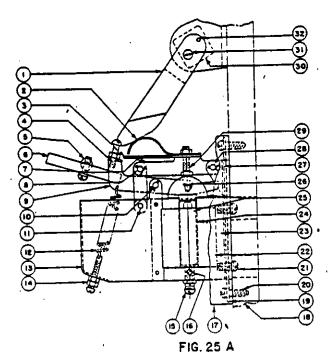
Now, when the breaker is opened and t reset arm (Pt. 1) is down, the disc shou be pressed firmly against the bottom of t dash pot by the buffer spring (Pt. 2) whi should now be about 1/32" to 1/8" from t flat spring (Pt. 3). If not, the buff spring will have to be bent to secure th clearance.

The adjustment of trip adjustment scr (Pt. 4) and the spring (Pt. 12) will be t same as in the instantaneous undervolta trip devices, described above.

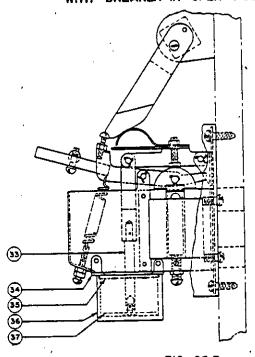
REVERSE CURRENT TRIP DEVICE (ROTOR TYPE)

A direct acting reverse current tr device of the rotor type, Fig. 26, is ava: able for the AE-1-25 breaker for direct cu rent application which will trip the break when the reversed current exceeds the cal bration setting. The device is construct similar to a bipolar motor with a station pole assembly in which is mounted a seri coil carrying the breaker current, and rotating armature on which is wound a] tential coil. The magnetic field set up the current in the potential coil toget! with the field set-up by the load current the series coil in the normal directia produces a torque which tends to rotate armature in a direction to prevent trippi However, when the current in the series c is reversed, the torque is reversed to ca the reverse rotation which trips the break

As shown in Fig. 26, the motor elem is mounted horizontally on the rear of mounting base by studs (Pt. 34). The arture shaft (Pt. 14) extends through to front to operate the tripping equipment. series coil (Pt. 5) is mounted vertically



INSTANTANEOUS UNDERVOLTAGE , TRIP DEVICE WITH BREAKER IN OPEN POSITION



IS FRAME

FIG. 25 B TIME DELAY UNDERVOLTAGE TRIP DEVICE WITH BREAKER IN OPEN POSITION

14. SPRING ADJUSTING SCREW RICL

-10-32 X 1 AND MUTS

L RESETTING ARM 2. BUFFER SPRING 3 FLAT SPRING 4. TRIP ADJUSTING SCREW R.H. 10-32 X \$ AND NUTS 5. BREAKER TRIP SHAFT 6. COMPOSITION TRIP ARM 7, RESET , LINK 8, PIN AND COTTER PINE & TRIP LEVER IO. PHI AND COTTER PHIS

IL STOP LINE

Z.SPRMG

- IS STOP SCREW R.HO. \$ -20X \$ WITH HEX HUT (DRECT CUMPENT ONLY) IE SCREW RIEL SELF TAPPING "4X2" 17. SARRIER IS, MOUNTING BASE 20. SCREW R.M. SELF-TAPPING "B X TIDNS AND LOCKWASHER 21. SCREW R.M. "10-32 X TI WITH LOCKWASHER 22, COIL 23, MAGNET
- 24. BRASS GUIDES 25. ARMATURE 26. PIN AND COTTER PINS 27. SUPPORT FOR PT. 7 28. PIN AND COTTER PIN 25. PRESET ADJUSTING SCREW HEX.HD.

 *10-32X \$ WITH NUT

 30. MAIN SHAFT

 31. SCREW R.H. *10-32X \$ WITH LOCKWISHER

 32. GROOV PIN TYPE 1, \$ DIA. X \$ 3

 33. PLUNGER ASSEMBLY 34. FRAME 35. COVER 36, OIL DASH POT 37. DISC

41) by screws (Pt. 3) and to the pole shoes (Pt. 43) by screws (Pt. 1). The upper part of the coil extends to the rear as a connection bar (Pt. 39) for external load connection which is supported by bar support (Pt. 40) held in place by screws (Pts. 3 and 4). The lower part of the coil is connected to the lower stud (Pt. 7) by connection bar (Pt. 8) and screw (Pt. 6).

The armature shaft (Pt. 14) is supported in bronze bearing castings (Pts. 33 and 38) which are fastened to the pole shoes by screws (Pt. 37) at the rear and by stude (Pt. 34) with nuts (Pt. 31) in spacer (Pt. 32) with nut housings at the front: An escutcheon plate (Pt. 30) is mounted on the front of the mounting base by nuts (Pt. 31) on stude (Pt. 34) and to it are riveted two posts for calibration plate (Pt. 18) and two posts for stop screws (Pts. 12 and 22). A trip crank (Pt. 13) is clamped firmly by screw (Pt. 15) and set screw (Pt. 16) to the extended armature shaft (Pt. 14) and supports the trip arm assembly (Pt. 25) on pin (Pt. 26). trip lever (Pt. 24) is screwed to the trip shaft (Pt. 23) and is free to move over the upper end of the rod between properly spaced jam nuts to permit sufficient travel when the breaker is tripped by other devices.

When current passes through the series coil in the normal direction, the armature will tend to revolve clockwise (looking from the front) to force the trip crank (Pt. 13). against stop screw (Pt. 22). The calibration spring (Pt. 20) also normally, holds the trip crank against this stop screw. But when current passes through the series coil in the reverse direction, the armature will tend to rotate counter-clockwise away from this stop screw, and when the current exceeds the calibration setting, it will rotate sufficient to lower the trip rod (Pt. 25) and trip the breaker. The stop screw (Pt. 12) limits the counter-clockwise travel. calibration plate (Pt. 18) is mounted on posts on the escutcheon plate. The calibration screw (Pt. 17) passes through these posts (Pt. 29) and carries a threaded calibration index (Pt. 19) attached to the calibration spring. By turning the hexagonal head of the calibration screw against the compression spring (Pt. 21), the reverse current trip setting can be changed.

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The trip crank is clamped to the armature shaft so that the potential coil (Pt. 44) will be located approximately in the vertical position with a somewhat larger air gap on the trip side when the crank is against the stop screw (Pt. 22), which should extend approximately 1/16" to 3/32" beyond the post-When rated voltage is applied to the potential coil with no current passing through the breaker and the calibration spring is connected, there should be no movement of the armature in the tripping direction. However, if a movement is detected, back off slightly on the stop screw (Pt. 22) to increase the

After this adjustment has been completed, the stop screw (Pt. 12) can be set to limit the travel of the armature so that the trip crank (Pt. 13) will be stopped slightly past the horizontal. Now adjust the nuts at the top of trip rod (Pt. 25) so that the breaker will trip with 1/32" overtravel of the trip lever measured at the trip lever. Slight variations of these adjustments may be necessary to improve the operation of the device.

The adjustment of stop screw (Pt. 22) and the tripping crank (Pt. 13) will affect the calibration of the reverse current device so their setting should not be changed unless facilities for checking calibration are available.

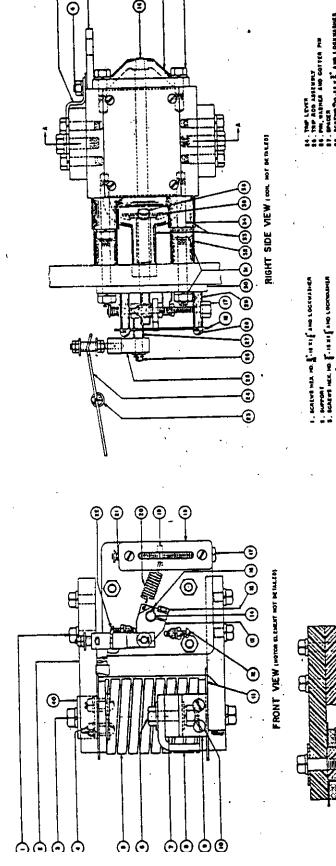
Because the potential must not drop below 80% of normal, the potential coil should be connected to a reliable constant potential source, preferably to a station battery bus, if possible.

REVERSE CURRENT TRIP DEVICE (HINGED ARMATURE)

A direct acting reverse current trip device of the magnet and hinged armature type is available for AE-1-25 breakers for direct current applications. It will operate to trip the breaker when the reverse current exceeds the calibration setting. The principle of operation is shown diagrammatically in Fig. 27, and in detail in Fig. 28A and B.

The device consists of a composite magnet with a series coil on the middle core, which carries the breaker current, and a potential coil on the bottom core. An air gap in the upper leg of the magnet is bridged by an armature which is attracted to the magnet and held by the flux from the potential coil alone, or more firmly when reinforced by the flux due to the current of the breaker through the series coil in the normal direction. But, when the current passes through the breaker in the reverse direction, the two fluxes are on longer cumulative and the flux across the air gap is weakened sufficiently to allow a spring to pull the armature away and trip the breaker.

The series coil (Pt. 4) is in the same location as the standard overcurrent coil, between the lower stud and the connection to the movable contact on the front of the breaker base. It is mounted on the middle core of the composite magnet (Pts. 2 and 6) while the potential coil (Pt. 9) is mounted on the bottom core. The magnet is provided with two thin non-magnetic spacers to provide with small magnetic gaps so placed to cause the greater part of both fluxes to flow through the upper leg of the magnet. The armature assembly (Pt. 11) is pivoted on pin (Pt. 10) which passes through the supporting frame (Pt. 12). The pivoted armature (Pt. 22) is held against the magnet to close the air gap when the potential coil is energized, and



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SECTION 'A A"

FIG. 26 REVERSE CURRENT TRIP DEVICE (ROTOR TYPE)

is held more firmly when the magnetic flux is increased by the breaker current in the normal direction.

When the current in the series coil reverses the magnetic pull on the pivoted armature (Pt. 22) in armature assembly (Pt. 11) decreases, and when the reverse current exceeds the calibration setting, the pull is not enough to overcome the pull of the spring (Pt. 15) which moves the armature away from the magnet. When the armature assembly is pulled away it strikes the trigger (Pt. 18) attached to the trip shaft (Pt. 19) which is supported in bearing plate (Pt. 20) attached to the frame by two screws (Pt. 21). This causes the trip shaft to revolve counterclockwise, (looking from left), to trip the breaker.

The magnetic pull produced by the potential coil alone will not draw the pivoted armature (Pt. 22) to close the air gap against the pull of the spring (Pt. 15) after the break has tripped due to reversed current, making it necessary to reset the armature as follows: - As soon as the breaker opens the main shaft (Pt. 23) and reset crank (Pt. 25) revolve clockwise (looking from left) and draw insulation link (Pt. 26) and link (Pt. 27) to the left. This link (Pt. 27) and reset lever (Pt. 30) are pivoted on the same pin (Pt. 28) and held together by torsion spring (Pt. 29) against lugs on each, so that when the reset lever (Pt. 30) is moved to the left it pushes the pivoted armature (Pt. 22) against the magnet (Pt. 2) where it is held by the magnetic pull of the potential coil (Pt. 9). The potential coil must be connected to the circuit so that it will be continously energized in order to hold the armature against the magnet when the breaker is tripped by other means than reversed current, otherwise the armature assembly will

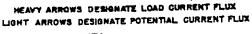
hold the trip shaft in the tripped position and the breaker will not close.

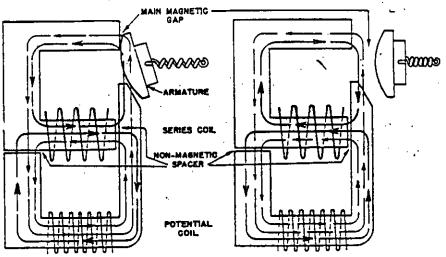
When the breaker is closed and the manishaft (Pt. 23) revolves counter-clockwise the reset linkage drives the reset leve (Pt. 30) away from the armature assembly (Pll) so that it will not retard the armature when released by reverse current.

Because the potential must not drop be low 80% of normal, the potential coil show be connected to a reliable constant potential source, preferable to a station battery but if possible.

When all the poles of a breaker requi: series coils for overcurrent trips, it i necessary to place the reverse current tr: device, of this type, "off pole" in the lo cation of an additional pole to the right (the regular poles. In this case, the sericoil is placed in series with the coil of : adjoining pole by placing a connection be between the lower study back of the mounting base. An upper stud is supplied for connetion to the source, or the load, as desire Extensions are provided for the main shaf and trip shaft to make provision for the re setting linkage and tripping. In such in stallations the current in the series col is in the opposite direction from standar practice in which case it will be importa that the potential coil should also be re versed.

For correct operation, the armature a magnet face must be kept clean. The armatushould be firmly seated against the top land the vertical leg of the magnet. If a justments are made to the reverse currer device, the calibration should be checked after the adjustments are made.





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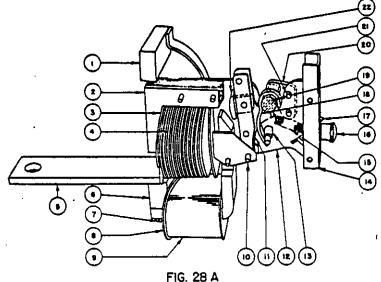
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RESISTOR REGURACO OVERCURRENT TRIP COLLS WHEN NUPPL KO REVERSE CURRENT TRE DEVICE

TRIPPED POSITION (WITH LEFT COVER AND RESET MECHANISM REMOVED)

WIRING DIAGRAM (BACK VIEW)

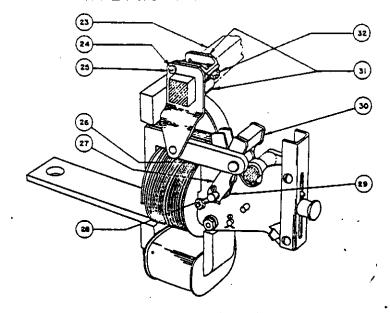
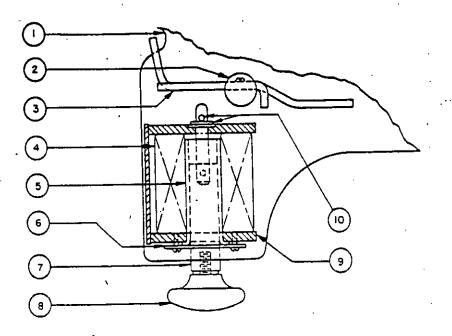


FIG. 28 B POTENTIAL COIL ENERGIZED AND BREAKER IN CLOSED POSITION

REVERSE CURRENT TRIP DEVICE (HINGED TYPE)

- I. TERMINAL OF SERIES COIL
- 2 LAMINATED SECTION OF MAGNET
- 1 INSULATION
- 4 SERIES COIL
- S. LOWER STUD
- & SOLID SECTION OF MAGNET
- 7. SCREW HEX. HO. \$ -20 X WITH LOCKWASHER
- & INSULATION
- & POTENTIAL GOIL ID. PIN AND COTTER FOR ARMATURE
- II. ARMATURE ASSEMBLY
- IZ. FRAMES
- IS. STOP PIN
- M. GALIBRATION PLATE
- IS CALIBRATION SPRING
- M. CALIBRATION KNOB
- IZ CALIBRATION INDEX AND SCREW
- IL TRIGGER IS TRIP SHAFT
- 20 BEARING PLATE
- EL SCREWS R.H. 10-32X WITH LOCK-WASHER
- 22 PIVOTED ARMATURE
- 23 MAIN SHAFT
- 24. SCREWS R.H. -- 20X WITH 25. RESET CRANK LOCKWASHER
- 26 INSULATION LINK
- 27.LINK
- 28 PIN AND GOTTER FOR LPM
- AND RESET LEVER
- 29. TORSION SPRPM
- SQRESET LEVER
- BLCRANK AND CLAMP BESCREWS HEX.HD. 1-80X WITH LOCKWAMMER



- I FRAME
- 2. TRIP SHAFT
- 3. TRIP ARM
- 4. COIL
- 5. GUIDE TUBE
- 6. WASHER
- 7. TRIP ARMATURE
- 8. BUTTON
- 9. MAGNET
- IO. COTTER PIN AND WAS

FIG. 29

SHUNT TRIP DEVICE

SHUNT TRIP DEVICE

A shunt trip device, Fig. 29, is available for AE-1-25 breakers which will trip the breaker when its coil is energized by closing a switch, or relay contacts, at some remote point. The coil is designed for intermittent service only, hence it should be so connected that the opening of the breaker, by any means, will open the shunt trip device circuit. The usual means is to place an "a", contact of an auxiliary switch in the shunt trip circuits, as shown in the wiring diagrams.

The device in the AE-1-25 breaker is mounted between the lower front part of the side plates that enclose the operating mechanism. It consists of a solenoid with a coil and armuture in a vertical position, and, when energized, the armature is lifted into the coil which causes a pin in the upper end to engage the trip arm (Pt. 3) and trip the breaker. When de-energized, the armature falls by its own weight to the normal position.

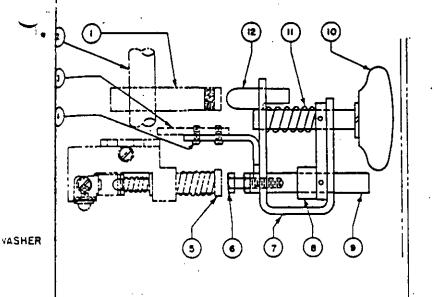
The coil (Pt. 4) is mounted over a brass guide tube (Pt. 5) within which the armature (Pt. 7) is free to move. The fall of the armature is limited by the travel of a cotter pin (Pt. 10) in the armature pin against brass and cork washers in the top of magnet (Pt. 9). The guide tube (Pt. 5) is held in place by washer (Pt. 6) which is attached by screws

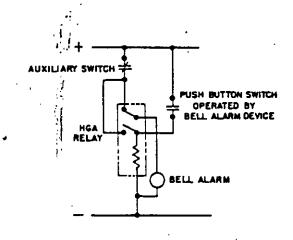
BELL ALARM DEVICE

This device, Fig. 30, together with HGA relay, and a push botton switch, simile to the operating switch, Fig. 16, and in same position, is designed to provide a meror silencing the bell alarm after the breakis automatically tripped and to prevent a bell alarm from ringing when the breaker manually tripped. It consists of a horiztally operated manual trip rod and butto and an additional rod operated simultaneou and to the left of the main trip rod assemb This latter rod operates the push butto switch. Fig. 30 shows a plan view of the device and a wiring diagram of connections.

When the breaker is tripped automatic ly, a "b" contact of the auxiliary switch closed to ring the bell alarm through normally closed contacts of an HGA relation when the hand trip button is operative normally open contacts of the push but switch are closed to close a circuit to ergize the relay. This opens the normal closed contacts of the relay to open the b circuit and seals in the relay, thus silence the bell.

When the breaker is tripped manually the trip button, the push button switch w be operated to energize the relay coil wh will de-energize the bell alarm circuit, fore the main trip rod will trip the break as described below, and prevent the operat





- 1. TRIP ARM (SEE FIG. IO)
- 2. BREAKER TRIP SHAFT (SEE FIG. 10)
- 3. LEFT FRAME OF OPERATING MECHANISM
- 4. SCREWS R.H. "10-32 X TE WITH LOCKWASHERS
- 5. PUSH BUTTON SWITCH (SEE FIG. 16)
- 6. ADJUSTING SCREW HEX. HD. #10-32 X I WITH LOCKNUT
- 7. BRACKET
- 8. YOKE WITH BOSS AND GROOV PINS
- 9. ROD
- IO. BUTTON AND LOCKWASHER
- 11. SPRING
- 12. TRIP ROD ASSEMBLY

FIG. 30

BELL ALARM DEVICE (PLAN VIEW)

The device consists of a bracket (Pt. 7) attached to the left side of the operating mechanism frame (Pt. 3) by screws (Pt. 4). The main trip rod assembly (Pt. 12) with a trip button (Pt. 10) passes through this bracket and engages the breaker trip arm (Pt. 1). Spring (Pt. 11) normally keeps it disengaged. Another rod (Pt. 9) passes through this bracket parallel to rod (Pt. 12) and is operated by a yoke (Pt. 8) so that both rods operate simultaneously in the same direction when button (Pt. 10) is pressed. An adjusting screw (Pt. 6), in the rear of the rod (Pt. 9), provides the adjustment that the push button switch will be operated before the breaker trip arm is engaged. Thus the button can be operated by the operator at will to silence the bell alarm after the breaker is tripped automatically, or to manually trip the breaker without ringing the bell alarm.

SAFETY INTERLOCK FOR ENCLOSED BREAKERS

The purpose of this interlock (Fig. 31) is to make provision that the breaker will be tripped whenever the door of an enclosing case is opened.

The trip rod (Pt. 5) operates horizontally in a molded trip rod guide (Pt. 7) and extends through to the front of a molded handle (Pt. 9), mounted on the front of the enclosing case door (Pt. 12). The guide has lugs on the right and left sides which allow it to slide horizontally through slots in the molded support (Pt. 15). The support is attached to bracket (Pt. 2), which is attached to the operating mechanism side frames (Pt. 1).

The molded handle (Pt. 9) is inserted through the door (Pt. 12) and is attached to it by screws (Pt. 10) through the nameplate (Pt. 11). Spring (Pt. 8), backed up by contracted turns in the rear of the handle, exerts pressure to seal the steel washer (Pt. 14) and felt washer (Pt. 13) against the inside of the door. The rear end of the handle is internally threaded, and is screwed over the threaded front end of the trip rod guide (Pt. 7) when the door is closed, and, in so doing, draws the trip rod guide forward to the position as shown in Fig. 31. Compression spring (Pt. 6), backed up against the bracket (Pt. 2), forces the trip rod forward through

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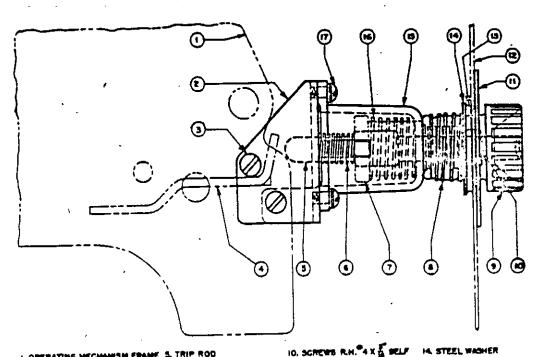
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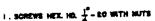


- I. OPERATING MECHANISM FRAME S. TRIP ROD
- 2. BRACKET
- 3. SCREWS RH. 10-32 X
- WITH LOCKWASHERS 4 TRIP LEVER
- & COMPRESSION SPRING

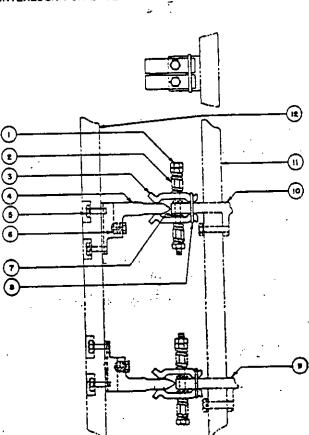
9. MOLDED HANGLE

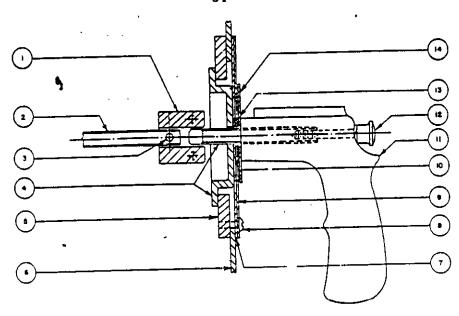
- TAPPHIS WITH LOCK
 - 15. MOLDED SUPPORT
- 7. MOLDED TRIP ROD GUIDE 11. NAME PLATE B. COMPRESSION SPRING 12. ENGLOSED CA IZ. ENGLOSED CASE DOOR
 - IS FELT WASHER
- IS. COMPRESSION SPRING 17. SCHEWS RIL 9-36X WITH WASHER AND LOCKWASHER

FIG. 31 INTERLOCK FOR ENGLOSED CASES



- 2. SPHWQS
- 3. CONTACT FINGER
- 4. STATIONARY STUD TERMINAL 5. SCREW HEX. HD. 18-18 X WITH LOCKWASHER
- S. SWIVELLED CABLE. GLAMP
- 7. WASHERS AND SHIMS
- S. RETAINING RING
- 9. BREAKER LOWER STUD 10. BREAKER UPPER STUD
- II. BREAKER BASE
- IL ENGLOSED CASE BASE





- I. COUPLING
- 2 SHAFT (a
- 3. SET SGREW 10-32 X ALLEN HD. CUP PT. 4. SHAFT AND BRAZED PLATE
- S. GLAMPING RING
- 4. STEEL DOOR
- 7. STEEL WASHER

- a , SGREWS R.H. **a-36 X $\frac{1}{2}$ WITH LOCKWASHERS
- 9 NAME PLATE
- 10. WASHER
- II. MOLDED HANGLE
- 12. KNOB AND LOCKWASHER
- 13, SHIM
- 14, WASHER

FIG.33
MANUAL OPERATING HANDLE ASSEMBLY SWITCHBOARD FRONT PLATE

rip lever (Pt. 7) and clear of the breaker rip lever (Pt. 4) when the door is closed. In this position the trip rod (Pt. 5) can be operated through the molded handle against compression spring (Pt. 6) to trip the breaker.

The design is such that the door cannot be opened until the handle is unscrewed from the trip rod guide (Pt. 7). When the handle is unscrewed, the compression spring (Pt. 16), backed up against the inside front end of the support (Pt. 15), forces the trip rod guide and trip rod to the rear to engage the breaker trip lever (Pt. 4) and trip the breaker whenever the door is opened.

DISCONNECTS FOR ENCLOSED BREAKERS

When type AE-1-25 breakers are to be installed in enclosed cases, spring maintained contact fingers are provided for both upper and lower studs. These have silver contact surfaces and automatically fit over stationary studs, with silver contact surfaces, mounted in the enclosed housing. Before the door of an enclosed case opens, Fig. 31, and before the breaker is removed from the enclosed case, the breaker is automatically opened, so that these contact fingers will not be called upon to open the breaker current, nor can the breaker be installed in the enclosure in the closed position.

Fig. 32 shows the contact fingers (Pt. attached to the breaker stude by screws.

(Pt. 1), springs (Pt. 2) and retaining rings (Pt. 8). The stationary stud terminals (Pt. 4) are mounted on a base (Pt. 12) in the enclosed case. Power cables are connected to stationary stud terminals with swivelled cable clamps (Pt. 6).

MANUAL OPERATING HANDLE ASSEMBLY FOR SWITCH-BOARD FRONT PLATES

On certain installations a disconnecting handle (Pt. 11) is provided and attached to the door to engage the shaft of the operating mechanism as shown in Fig. 33.

A clamping ring (Pt. 5) is attached to the steel door (Pt. 6) by three screws (Pt. 8) which pass through the nameplate (Pt. 9) and steel washer (Pt. 7). The shaft and plate (Pt. 4) are brazed together and pass through the door from the rear. Handle (Pt. 11), washer (Pt. 14) shim (Pt. 13) and washer (Pt. 10) are attached to the front of the shaft by knob (Pt. 12). When the door closes the rear end of the shaft (Pt. 4) engages coupling (Pt. 1) which is attached to shaft (Pt. 2) of the operating mechanism by set screw (Pt. 3).

To prevent undue friction in the movement of the handle it is recommended that a lubricant should be applied to the engaging surfaces between shaft and plate (Pt. 4) and the clamping ring (Pt. 5). Lubricate #130-A, G.E. Spec. D50E10 should be used.

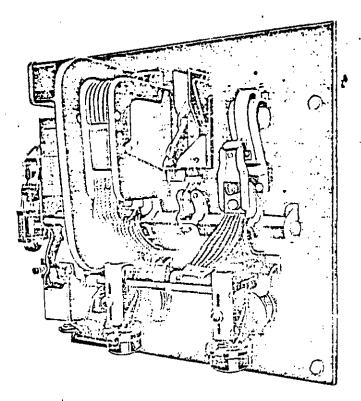


FIG. 34
ELECTRICALLY OPERATED TYPE AEF-1 FIELD SWITCH (LIVE FRONT).

TYPE AEF-I FIELD SWITCH

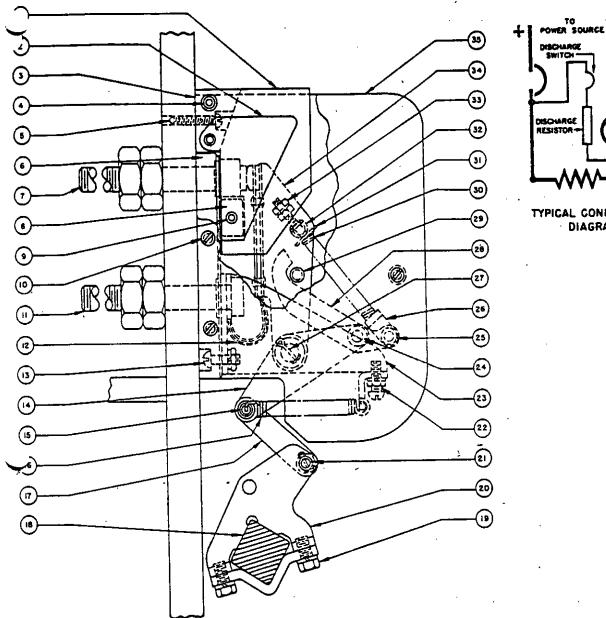
The type AEF-1 field switch, Fig. 34, isused for the control of generator or motor shunt field circuits. It consists of a regular two pole type AE-1-25 air circuit breaker, manually or electrically operated, automatic or non-automatic, as described herein, but equipped with a field discharge switch placed between the two main poles of the field switch. The contacts of the discharge switch are closed and opened by a self-contained mechanism connected to the main shaft of the field switch. The discharge switch is operated and constructed, as described below, to connect a discharge resistor across the shunt field terminals when the field switch opens the field circuit. The connection of this resistor prevents a high induced voltage across the field terminals caused by the rapid collapse of flux in the magnetic circuit of the shunt field.

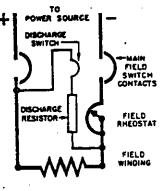
This field switch is not used with synchronous condensers or synchronous motors which start on alternating current as induction motors at full or reduced voltage.

FIELD DISCHARGE SWITCH

The field discharge switch, Fig. 35 of the AEF-1 field switch consists of an upper stud (Pt. 7) with a silver alloy contact, a lower stud (Pt. 11) both mounted through the bases of both the field switch and the pivoted on pin (Pt. 27) in the frame and an operating mechanism. The cont is connected to the lower stud by a connection (Pt. 12) and has a silve contact at the top which registers similar contact on the unper stud. shaft (Pt. 18) is connected to the lever by crank (Pt. 20), link (Pt. (Pt. 14), catch (Pt. 28) and spring 26) as described below so that when shaft revolves clockwise (looking) left) to open the field circuit, the of the discharge switch will positive before the contacts of the field swill The closing of these contacts conne discharge resistor directly across minals of the shunt field to discha induced high voltage in the field, in the accompanying connection diagra 35 shows the discharge switch in th tion.

When the main shaft revolves (clockwise to close the main contact field switch, the spring rod (Pt. pulled forward through pin (Pt. 32) contact lever against the pressure pression spring (Pt. 30), but beflocknuts (Pt. 33) engage the pin, t. (Pt. 28) engages rivet (Pt. 29) als contact lever, and draws the contact forward to open the contacts far apart as the lower end of catch (Pt. 28) over the kick-off screw (Pt. 22) as crum, the catch diseases the rive





TYPICAL CONNECTION · DIAGRAM

- 1. BARRIER FOR ARC CHUTE
- 2 POLE PIECE OF ARC CHUTE
- 3. SUPPORT FOR ARC CHUTE
- 4 RIVETED PIN
- 5. SCREW R.H. SELF TAPPING #6 X I
- & BASE
- 7. UPPER STUD AND CONTACT
- 8. MAGNET
- 9. RIVETED PIN
- IO. SCREW R.H. SELF TAPPING #8 X 3 FOR PT. 35
- II. LOWER STUD
- 12. FLEXIBLE CORNECTION (INCLUDED IN PT. 34)

- 13. SCREW R.H. TIO-32 X T WITH LOCKWASHER AND NUT
- 14. CRANK
- 15. PIN AND SPACER
- IS. TENSION SPRING
- IT. LINK
- IS, MAIN SHAFT
- 19. SCREW HEX, HD. 1 20 X WITH LOCKWASHER
- 20. CRANK AND CLAMP
- 21, PIN, COTTER PIN AND SPACER
- 22. SCREW R.H.#10-32 X T WITH LOCKWASHER AND NUT
- 23. FRAME
- 24. RIVET AND WASHERS

- 25. RIVET
- 26. SPRING ROD
- 27. PIN, COTTER PIN AND SPACER
- 28. CATCH
- 29. RIVET
- 30. COMPRESSION SPRING
- 31. WASHER
- 32. PIN
- 33 LOCKNUTS AND LOCKWASHER
- 34 CONTACT LEVER
- 35. BARRIER FOR LIVE FRONT SWITCHES

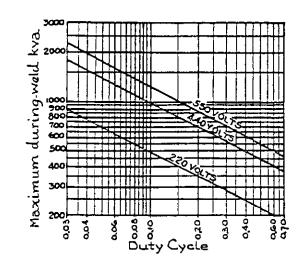
FIG. 35 FIELD DISCHARGE SWITCH WITH FIELD SWITCH IN OPEN POSITION to the rear allows compression spring (Pt. 30) to force the contact lever in the closing direction but the contacts do not close because pin (Pt. 32) is stopped by the locknuts to keep the contacts apart 1/8 of an inch.

Then when the field switch opens and the main shaft revolves clockwise, the spring rod and locknuts move to the rear to close the discharge switch contacts.

An arc chute encloses the contacts with a barrier (Pt. 1) and pole pieces (Pt. 2) on each side and supported to the field switch base by support (Pt. 3), rivets (Pt. 4) and self-tapping screw (Pt. 5). A magnet (Pt. 8) is supported between the barriers below the upper stud (Pt. 7) by rivet (Pt. 9). In live front field switches barriers (Pt. 35) are attached to the discharge switch base (Pt. 6) by self-tapping screws (Pt. 10).

The first adjustment consists of adjusting the kickoff screw (Pt. 22) so that the catch (Pt. 28) disengages rivet (Pt. 29) just before the field switch is fully closed.

The second adjustment consists of adjusting the locknuts (Pt. 33) on spring rod (Pt. 26) until the contacts of the discharge switch are 1/8 of an inch apart when the field switch is fully closed.

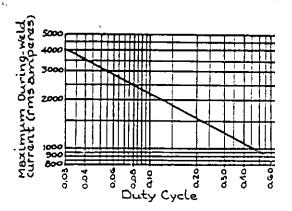


TYPE AE-1-25YI AIR CIRCUIT BI

This breaker is designed for the tion of resistance welding machines stantaneously trip at higher current than provided with the regular insta overcurrent trip device as shown in The breaker differs from the regula AE-1-25 breaker only in the provision tain higher current settings. This a special trip shaft to allow large ture travel of the instantaneous ove trip device for current settings absamperes.

Standard calibration ranges ar 1500 amperes, 1400 to 4000 amperes to 5000 amperes. Within reasonable other ranges can be proceed where t est calibration settings will not approximately 2-1/2 times the lowes bration setting.

As the duty imposed on the AE breaker is intermittent and quite v depending upon various types of wel be done, the breaker is not given a ous current rating. It is designed t carry "during-weld amperes" or "duri KVA" at welding periods not to exce corresponding "duty-cycle" as tabul Fig. 35.



	During-	D	uring-weld KV	A
Duty Cycle	weld AMP Rms	220 Volts	440 Volts	550 Volta
0.03	4040	890	1780	2225
.04	3500	770	1540	© 1925
.05	3130	689	1378	1722
.06	2860	629	1258	1574
.07	2640	580	1161	1453
.08	2740	544	1087	1360
.09	2330	513	1025	1282
.10	2215	487	974	1219
.20	1566	345	689	861
.30	1278	281	562	703
.40	1107	244	487	609
.50	990	218	436	545

WIRING DIAGRAMS

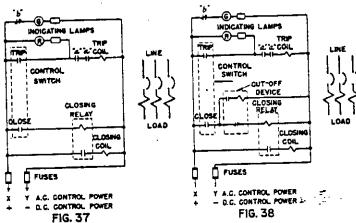
Figs. 37 and 38 show schematic wiring diagrams for electrically operated AE-1-25 breakers with momentary and maintained contact control switches respectively. Pig. 39 and 40 show typical wiring diagrams with the

momentary and maintained contact control switches respectively.

The standard arrangement for direct current circuits is to have voltage coils connected solidly to the negative bus or line where possible.

CUT-OFF DEVICE FIG. IT IS MECHANICALLY PICKED UP BY CLOSING MECHANISM OF BREAKER

M-AUX. SW. OPEN WHEN BREAKER IS OPEN. "MIX. SW. GLOSED WHEN BREAKER IS OPEN. 46 - CONTACT OPEN WHEN DEVICE IS IN THE DE-ENERGIZED OR NON-OPERATED POSITION. AF - CONTACT CLOSED WHEN DEVICE IS IN THE DE-ENERGIZED OR NON-OPERATED POSITION.



SCHEMATIC WIRING
FOR ELECTRICALLY OPERATED AE4-ES BREAKER
WITH MOMENTARY CONTACT CONTROL SMITCH

SCHEMATIC WIRING
FOR ELECTRICALLY OPERATED AE-1-25 BREAKER
WITH MAINTAINED CONTACT CONTROL SWITCH

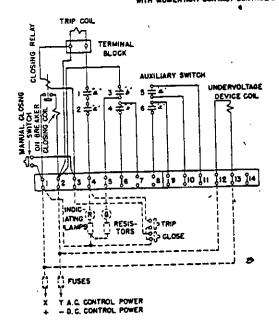


FIG. 39
TYPICAL WIRING DIAGRAM
FOR ELECTRICALLY OPERATED AE-1-26 BREAKER
WITH MOMENTARY CONTACT CONTROL SWITCH

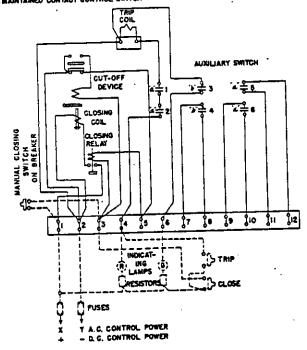


FIG. 40.

TYPICAL WIRING DIAGRAM
FOR ELECTRICALLY OPERATED AE-1-28 MEAKER
WITH MAINTAINED CONTACT CONTROL SWITCH

SPARE PARTS

		3	PARE	PARIS			
***	P	t. F	ig.	Item		Pt.	F1g
Item	ACT STUDS, POLE UNIT ASSEMBLY			27	Screw RE 1/4"-20 with Wash-		
				21	er, Lockwasher and Nut	18	8
1	Upper Stud, Blowout Coil and Arc Runner Assembly4,	6.30	8		Screw RH $1/4$ *-20 with Vash-		<u>.</u>
	Upper Stud, Blowout Coil and	_,		•	CI DOCK COMPT CITY	14	7.
	Arc Runner Assembly	7	7		Screw RH 1/4"-20 with Wash- er, Lockwasher and Nut	2	8
2	comice Coil Lower Stud As-			28	Screws Hex. Hd. 1/4"-20 with	~	
_	semblySee Overcurrent	29 .	. 8		Washer and Lockwasher	15'	7
3	Insulation	2	8		Screws Hex. Hd. 1/4"-20 with	_	10
4		.6	7		Washer and Lockwasher	3	18
5	Ingulation	3	8	29	Screws RH 1/4-20 with Lock washers	17	7
6	Stationary Arcing Contact	28	8		Screws RH 1/4-20 v .h Lock-		
7	Screws RE 5/16-18 with look-	1	8		washers	6	18
	Screws RE 5/16-18 with lock-	-	•		Screws RH 1/4-20 with Lock-		
	washer	5	7		washers	10	26 7
8	Screws RH #10-32 with Washer	_	_	30	Trip Shaft	20 18	10
•	and Lockwasher	5	8		" "	5	25
	Screws RH #10-32 with Washer	8	7		и и	19	28
_	and Lockwasher	0	•	•	# N	2	29
9	Lockwashers	25	8	•	# #	2	30
10	Bracket	8	8				
		11	7	ARC	QUENCHER		
	***************	7 9	18 26	31	Side Plates	23	7
	on 1/4 00 with Lock-	9	20	32	Support for Arc Quencher	1	7
11	Screws RH 1/4-20 with Lock- washer and Nut	7	8	33	Screw RH 5/8"-18 with Lock-	_	_
	Screws RH 1/4-20 with Lock-				washer	2	
	washer and Nut	9	7	34	Locking Plate and Self-Tap- ping Screws	3	7
	Screws RH 1/4-20 with Lock-	L.	10	35	Screws RH #10-32 x 2-1/2	Ū	•
	washer and Nut.	6	18	30	with Lockwashers and Nuts	4	7
12	Screws Hex. Hd. 1/4"-20 with Lockwasher	17	7	36	Pole Piece Plates	35	7
	Screws Hex. Hd. 1/4"-20 with			37	Screws RH. #10-32 x 2-3/4	20	
	Lockwasher	18	8		with Lockwasher and Nuts	28	Ĭ
	Screws Hex. Hd. 1/4"-20 with	_	30.	20	Front Arc Runners	26	7
	Lockwasher	8	18	38 39	Insulation Blocks	30	•
13	Movable contact and Silver	24	8.	40	Screws RE #10-32 x 1/4" with		
	Contact	27	8		Lockwasher and Washer	25	,
. 14 . 15		•		41	Screws FR #10-32 x 1/2	29	·
. 10	Lookwaahar	26	8	42	Screws R.H. #10-32 x 1/2 with Lockwashers and Nuts	27	4
16	Adjusting Screw RH 5/16" -			42	Baffles	31	, , ,
	18 x 1-1/4 with washer, Lock	• 22	. 8	43 44	Screws R.H. #10-32 x 2-5/8"		
	washer and Nut	23	0		with Lockwashers and Nuts	34	1
17	Screw Hex. Hd. 5/16"-18 x 7/8" with Lockwasher and			45	Pins. Copper	33	
	Washer	21	8	46	Pins, High Melting Point	32	
18	Pin and Cotter Pins	22	8	,	•		
19	Contact Support	13	8	OPE	RATING MECHANISM		
	n n	. 12 . 15	7 8				
20	Clamp	. 10		47	Manual Closing Handle	23	1
21	Screw, Hex. Ed. #4-20 x 5/8" with Lockwasher	16	.8	48	Eccentric Shaft	1	1
22		12	8	49	Link	2	1
23	Spring Guide	10	8	50	Block and Guide Pin	3,4	1
24	Pin	11	8	51	PinClosing Links	6	· î
25	Hain Shaft	14 13	8 7	52 53	Toggle Links, A,B,C,D	8	1
	* # *************	29	10	54	Pin in Frame	9	1
	7	30	25	55	Pin in Frame	10	1
	M . M	18	34	56	Torsion Spring	11	1
26		19,20	8	57 58	Latch	12	1
-	-	~. ^^		~ 2	WITH THE STREET A A A A A A A A A A A A A A A A A A		-

<u>I</u> †^=	Pt.	Fig.	Item	Pt.	Fig.
Spring	. 14	10	102 Cover	5	15
60 Prop		10	103 Cam and Toothed Bushing	6	15
61 Latch Plate	. 17	ĩõ	104 End Frame	7	15
62 Frame	. 19	, 10	105 Crank, Pin and Cotter Pin	8	15
*		13	106 Link	ğ	15
*	_	17	107 Shaft	10	15
*	_	30	•		
63 Trip Arm		10	OPERATING SWITCH		
# R		29			
H N		30	108 Mounting Bracket	12	16
A A	. 4	31	109 Screw R.H. #8-36 x 3/4 with		
64 Pin in Frame	. 21	10	Nut and Lockwasher	11	16
65 Cam		10	110 Molded Base	8	16
66 Outer and Inner Springs	. 25	• 10	lll Contact Brackets and Bind-		
67 Spring Guide	. 24	10	ing Screws	1	16
68 Cam Stop Pin	. 26	ຸ 10	112 Screw R.H. #10-32 x 3/4 with		
69 Operating Cam	. 27	10	Lockwasher	13	16
70 Bracket	. 28	10	113 Operating Rod	10	16
•			114 Spring	9	16
ADJUSTMENT ECCENTRICS FOR TRIP	LRM AND	LATCH	115 Washer	7	16
			116 Contact Spring	6	16
71 Eccentric with 1/4"-20		1	117 Insulation	5	16
Threaded Shank	. 4	11	118 Movable Contact Strip	4	16
72 Nut $1/4^n$ -20	3	11	119 Guide	3	16
73 Eccentric	8	11	120 Screw R.H. #4-40 x 1-1/4	_	
74 Screw, Hex. Hd. #10-32 x	_		with Washers	2	16
7/16" with Lockwasher	. 9	11			
75 Buffer Spring	10	11	CUT-OFF DEVICE		
SOLENOID OPERATING MECHANISM			121 Flanged Bracket	2	17
			122 Pin and Cotter Pin in		
76 Magnet	1	13	Bracket	4	17
77 Coil		13	123 Flat Spring.	5	17
Armature		13	124 Pin in Armature	6	17
Pin in Armature	5	13	125 Screws R.H. #8-36 x 3/8"		
и п и		17	with Lockwashers	7	17
80 Pin in Frame	6	13	126 Magnet	10	17
81 Maintenance Closing Handle.	· 7 ·	13	127 Coil	11	17
			128 Armature	8	17 -
CLOSING RELAY			129 Brass Guides	9	17
			130 Pin in Armature	13	17 17
82 Magnet	1	14	131 Washer and Cotter Pin	12 14	17
83 Coll		14	132 Screw and Locknut	==	17
84 Brass Guide		14	133 Operating Rod	15	17
85 Armature		14	134 Spring	, 10	11
86 Stationary Contacts	5	14	135 Contact Brackets and Bind-	17	17
87 Binding Screws and Lock-	•	14	ing Screws	18	17
washers		14 14	136 Movable Contact Strips 137 Contact Spring	19	117
88 Movable Contact Assembly		14	138 Guide	20	17
59 Pin and Cotter Pin		14	139 Screw, R.H. #4-40 x 1-1/4		
90 Insulation Angle	•• 3	7.3	with Washers	21	17
91 Screw, R.H. Self-Tapping #8 x 3/8 with Lockwasher	10	14	140 Screw R.E. #8-36 x 3/4		
92 Relay Base		14	with Lockwasher and Nut	1	17
93 Screw F.R. #10-32 x 3/4"	12	14	141 Molded Base	22.	17
94 Screw FH #8-36 x 1/2	13	14	142 Screw R.H. #8-35 x 3/4" with		
95 Screw RH #10-32 with Lock-			Lockwasher and Nut	1	17
washer and Nut	15	14		_	
96 Screw R.H. Self-Tapping #6			MAGNETIC OVERCURRENT TRIP DEVICE	(OIL-	FILM
x 3/16"	18	14	TYPE)	. –	
97 Screw R.H. Self-Tapping #4	••		/		
x 1/4"	17	14	143 Series Coil, Lower Stud and		
~ -/	- 		Terminal	5,9	18
ROTARY TYPE AUXILIARY SWITCH			Series Coil, Lower Stud and	•	
THE PERSON WAS IN STANDARD SHOPE ALL WAS AND			Terminal	3,4	23
98 Molded Barriers	1	15	Series Coil, Lower Stud and	-	
S Movable Contact Assembly		15	Terminal	4,5	28
Stationary Contact Assembly	3	15	144 Magnet	4	18
11 Stationary Contact Support.	4	15	Ñ	2	23

Item	Pt.	Fig.	Item Pt.
145 Insulating Tube	10	18	MAGNETIC INSTANTANEOUS OVERCURRENT TRIP DE
146 Insulating Washers	11	18	(See Dual Oil Film Magnetic Overcurrent
140 11104784579	3.	28	Device for Common Parts).
147 Frame	12	18	bin Chan
*	5	23	195 Armature assembly and Stop
148 Armature Assembly	_1	18	
149 Pin and Cotter Pins	13	18	196 Stop Screw and Hex. Nut 7 197 Support 8
, n n n n n n n n n n n n n n n n n n n	6	23	198 Lower Stud
150 Calibration Spring	21	18	199 Brass Plate and Rod 2,10
*	10	23	200 Screws F.H. #10-32 x 1* 3
151 Calibration Index and Screw	23 12	18 23	201 Magnet 4
n n n n n n n n n	22	18	202 Screws R.H. #16-32 x 7/16
152 Calibration Adjusting Knob.	ĩĩ	23	with Lockwashers
153 Calibration Plate	27	18	203 Brass Guides 6
153 Calibration Place	14	23	204 Armature, Guide Roll and
154 Screws R.H. #8-36 x 1/4			Trip Arm
with Washers	26	18	205 Nuts 1/4"-209
Screws R.H. #8-36 x 1/4			206 Brass Tube
with Washers	13	23	207 Compression Spring 13
155 Pivoted Cover and Support	14	18	208 Brass Cup 14
156 011 Pot	15	18	
157 Lower Disc	16	18	UNDERVOLTAGE TRIP DEVICE
158 Upper Disc	17	18 .	UNDBILLO
159 Shank	18	18	200 Regat Arm
160 Spring	19.	18	ZUS RESEV MANAGEMENT
161 Instantaneous Spring	20	18	ZIO DOLLOL DEL MIG
162 Adjusting Stop	. 24	18	211 Flat Spring
163 Screws Hex. Hd. #10-32 X			#10-32 x 5/8 and Nut 4
1/2" with Nuts and Washers.	25	. 18	213 Arip Arm 6
164 Trip Finger	28	18	214 Reset Link
m n	15	23	215 Pin and Cotter Pins 8
	TD DE	VTCV	216 Trip Lever 9
THERMAL MAGNETIC OVERCURRENT TR	מת אז	1108	217 Pin and Cotter Pins 10
	4	20	218 Stop Link
165 Molded Frame	6	20	219 Spring
166 Magnet	5	20	220 Frame
167 Coil	19	20	221 Adjusting Screw R.H. #10-32
169 Spring Hinge	14	20	$_{\rm X}$ 1-1/2" and Nuts 14
170 Yoke	20	20	222 Stop Screw R.H. 1/4"-20 x
171 Pin	28	20	5/8" with Nut
172 Short Circuit Spring	1	20	223 Screw R.H. Self-Tapping #4
173 Spring Guide and Locknut	2	20	A 1/7 1000 1000 1000 1000 1000 1000 1000
174 Tubular Spring Guide and			AAA Dali Ac
Cotter Pin	3	20	225 Mounting Strap 19 226 Screws R.H. Self-Tapping #8
175 Pin in Armature and Yoke	25	20	x 7/8" and Lockwasher 20
176 Flat Buffer Springs	22	20	227 Screws R.H. #10-32 x 1/2
177 Leather Washer	24	20 20	with Lockwasher21
178 Adjusting Screw and Spring.	21	40	228 Coil22
179 Armature Adjusting Screw	23	20	229 Magnet
and Nut		20	230 Brass Guides 24
180 Reset Spring for Yoke	27	20	231 Armature 23
181 Adjusting Screw	-	20	232 Pin and Cotter Pins 26
182 Bimetallic Thermal Strip	7	20	233 Support for Pt. 7
183 Induction Ring	1 1	20	234 Pin and Cotter Pins 28
184 Pin		20	235 Adjusting Screw Hex. Hd.
185 Thermal Trip Arm	•	20	$\#10-32 \times 5/8$ " with Nut 29
186 Latch Support		20	236 Screw R.H. #10-32 x 1/2"
187 Torsion Spring on Pt. 8 188 Adjusting Screw	12	20	with Lockwasher 31
189 Latch Plate	15	20	237 Groov Pin Type 1/8" dia
190 Spring for Thermal Trip Arr		20	D/A" IURK
190 Spring for industrial 1117 1119	1	•	238 Plunker Assembly
Cotter Pin	• T9	20	Min Prince
192 Calibration Knob	. 17	20	240 Cover
		^^	THE THE LINES WILL

				4 -		
<u>Item</u>	t	Pt.	Fig.	Item	Pt.	Fig.
\	man amporte wath helitor			288 Insulation Washer	8	28A
-Œ YE	RSE CURRENT TRIP DEVICE			289 Potential Coil	9	28A
0.40	Stop Codl and Composition			290 Pin and Cotter Pin	10	284
243	Series Coil and Connection	5	26	291 Armature Assembly	11 .	28A
244	Core	41	26	292 Frame	12	281
	Screws Hex. Hd. 3/8"-16 x			293 Pivoted Armature	22	28A
	1-1/4 with Lockwasher	3	26	294 Stop Pin	13	28A
248	Supports	2	26	295 Trigger	18	28A
	Upper Connection Bar Sup-	-		296 Bearing Plate	20	28A
471	port	40	26	297 Screws R.H. #10-32 x 3/8"		
248	Screws R.H. 1/4"-20 x 1"			with Lockwasher	21	28A
~10	with Lockwashers and Nuts			298 Calibration Plate	14	28A
	and Insulating Washers and		•	299 Calibration Spring	15	28A
	Bushings	4	26	300 Calibration Knob	16	28A
249	Screws Hex. Ed. J/8-16 x			301 Calibration Index and Screw	17	28A
~	1-1/2" with Washer, Lock-		•	302 Reset Crank	25	28B
	washer and Nut	6	26	303 Screw Hex. Hd. 1/47-20 x		
250	Lower Stud	7	26	1/2" with Lockwasher	24	28B
	Insulation Tube	42	26	304 Insulation Link	26	28B
	Insulation Washers	11	, 26	305 Link	27	28B
	Screws, Hex. Hd. 5/16-18 x		•	306 Pin and Cotter Pins	28	28B
~~~	1-1/4 with Lockwashers	1	26	307 Torsion Spring	29	283
254	Armature Shaft	14	- 26	308 Reset Lever	30	28B
	Rear Bronze Bearing	38	26	309 Crank and Clamp	31	28B
	Screws, Hex. Hd. 5/16-18 x			310 Screws Hex. Hd. 1/4-20 x		
~00	7/8" with Lockwashers	37	26	5/8" with Lockwasher	32	28B
257	Front Bronze Bearing	33	26	,		
	Studs	34	26	SHUNT TRIP		
259	Nuts, Hex. 5/16-18 with					
	Lockwashers	31	26	311 Coil	4	29
260	Spacers with Nut Housings	32	26	312 Guide Tube	5	29
	Thrust Washer and Insulation			313 Washer	6	29
	Washers	35	26	314 Trip Armature	7	29
<b>`62</b>	Grommet	36	26	315 Button	8	29
	Armature	45	26	316 Magnet	9	29
264	Coil	44	26	317 Cotter Pin and Washer	10	29
265	Pole Shoes	43	26			
	Dust Covers	46	26	BELL ALARM DEVICE		
267	Screws, R.H. Self-Tapping				~	20
	#8 x 3/8" with Washer and			318 Bracket	7	30
	Lockwasher	47	26	319 Screws R.H. #10-32 x 5/16"	4	20
268	Escutcheon Plate	30 ·	26	with Lockwashers	4	30
269	Posts	29	26	320 Adjusting Screw Hex. Hd.		
	Trip Crank	13	26	#10-32 x 1-1/8" with Lock-	6	30
271	Screw, Hex. Rd. #10-32 x			Out Docs and Groov	·	30
	9/16* and Lockwasher	15	26	321 Yoke with Boss and Groov	8	30
272	Set Screw, Cup Point #8-36		•	Pins	9	30
	x 1/8"	16	26 26	323 Button and Lockwasher	10	30
	Calibration Spring	20	26	324 Spring	11	30
	Calibration Index	19	26 26	325 Trip Rod Assembly	12	30
	Calibration Plate	18	20	SES ITEP NOW MEDICALLY CONTROL		
276	Screws, R.H. #10-32 x 3/8"		26	INTERLOCK FOR ENCLOSED BREAKERS		
	with Lockwasher	28	20	111111111111111111111111111111111111111		
277	Calibration Screw Hex. Hd.	17	26	326 Bracket	2	31
880	Washer and Cotter Pin	21	26	327 Screw R.H. #10-32 x 5" with		
	Compression Spring	~ .		Lockwasher	3	31
279	Stop Screw with Lockwasher	12	26	328 Trip Rod	5	31
200	and Nut, Reverse		20	329 Compression Spring	. 6	31
280	Stop Screw with Lockwasher	22	26	330 Molded Trip Rod Guide	7	31
201	and Nut, Normal	26	26	331 Compression Spring	8	31
	Pin, Washer and Cotter Pin.	27	26	332 Molded Handle	9	31
	Trip Rod Assembly	25	26	333 Screws, R.H. #4 x 3/16"		
	Trip Lever	24	26	Self-Tapping with Lock-		
	-			washer	10	31
REVI	erse current trip device (Hinge	U ARM	ATURE)	334 Nameplate	11	31
285	Laminated Section of Magnet.	2	28A	335 Felt Washer	13	31
	Solid Section of Magnet	6	28A	336 Steel Washer	14	31
2287	Screw Fil. Hd. A, 1/4"-20			337 Molded Support	15	31
**	x 3/4"	7	28A	338 Compression Spring	16	31

			-,,	-Pt:	Fig.
Item	Pt.	Fig.	Item		
			365 Support for Arc Chute	3	35
339 Screws, R.H. #8-36 x 1/2"	17	· 31	366 Riveted Pin	4	35
with Washer and Lockwasher	1,	41	367 Screws, R.H. Self-Tapping	•	
DISCONNECTS FOR ENCLOSED BREAKERS			#6 x 1"	5	35
DISCOUNDED FOR THOSE OF THE			388 Base	6	35
340 Screws, Hex. Hd. 1/4"-20 x	,	32	369 Upper Stud and Contact and		-
A with Nuts	1	32	Nuts	7.	35
341 Springs	2 3	32	370 Magnet	8	35
- ウォリーでものものでも、光1の気管で見る。。。。・・・・・・・・・・・・	3 4	32	371 Riveted Pin	9	35
143 Stationary Stud Terminal	4	34	372 Screws R.H. Self-Tapping		
RAA Screws Hex. HQ. 3/10-10 A	5	32	#8 x 3/8"	10	35
3/4 with Lockwasher	6	32	373 Lower Stud and Nuts	11	35
345 Swivelled cable clamp	7	32	374 Screws R.H. #10-32 x 5/8"		
346 Washers and Shims	8	32	with Lockwasher and Nut	13	35
347 Retaining Ring	9	32	375 Crank	14	35
348 Breaker Lower Stud	10	32	376 Pin and Spacer	15	35
349 Breaker Upper Stud	12	32	377 Torsion Spring	16	35
350 Enclosed Case Base	1,2,		378 Idnk	17	35
A CONTRACT OF CONT	2012 61	בורייידע	379 Screws, Hex. Hd. 1/4"-20 x		
MANUAL OPERATING HANDLE ASSEMBLY	on a	M I I OM	5/8" with Lockwasher	19	35
BOARD FRONT PLATES			380 Crank and Clamp	20	35
	1	33	381 Pin. Cotter Pins and Spacer	21	35
351 Coupling	3	33	382 Screw, R.H. #10-32 x 5/8"		
352 Set Screw	4	33	with Lockwasher and Nut	22	35
353 Shaft and Plate	5	33	383 Frame	23	35
354 Clamp Ring	7	33	384 Rivet and Washers	24	35
THE STEEL WASher		00	385 Rivet	25	35
356 Screws R.H. #8-36 x 1/2	8	33	386 Spring Rod	26	35
with Lockwashers	_	33	387 Pin. Cotter Pins and Spacer	. 27	35
357 Nameplate	_	33	388 Catch	28	35
358 Washer.		33	389 Rivet Stop	29	35
359 Molded Handle		33	390 Compression Spring	30	35 35
360 Knob	13	33	391 Washer	31	35 35
361 Shim		33	392 Pin	32	35 35
362 Washer	1-1	00	393 Locknuts and Lockwasher	33	35
FIELD DISCHARGE SWITCH			394 Contact Arm and Flexible		n E
	1	35	Connection	34	35
363 Barrier for Arc Chute	2	35	395 Barrier	35	35
364 Pole Piece for Arc Chute	4				