

## Signal targets for PosSTW (positioning mode, r0108.4 = 1)

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Signal	Meaning	Interconnection parameters	[Function diagram] internal control word	[Function diagram] signal target	Inverted
PosSTW1.0	<b>1 = Tracking mode</b> 0 = No tracking mode	p2655 = r2092.0	-	[3635]	-
PosSTW1.1	<b>1 = Set home position</b> 0 = Do not set home position	p2596 = r2092.1	-	[3612]	-
PosSTW1.2	<b>1 = Reference cam active</b>	p2612 = r2092.2	-	[3612]	-
PosSTW1.3	<b>Reserved</b>	-	-	-	-
PosSTW1.4	<b>Reserved</b>	-	-	-	-
PosSTW1.5	<b>1 = Jogging, incremental active</b> 0 = Jogging, velocity active	p2591 = r2092.5	-	[3610]	-
PosSTW1.6	<b>Reserved</b>	-	-	-	-
PosSTW1.7	<b>Reserved</b>	-	-	-	-
PosSTW1.8	<b>Reserved</b>	-	-	-	-
PosSTW1.9	<b>Reserved</b>	-	-	-	-
PosSTW1.10	<b>Reserved</b>	-	-	-	-
PosSTW1.11	<b>Reserved</b>	-	-	-	-
PosSTW1.12	<b>Reserved</b>	-	-	-	-
PosSTW1.13	<b>Reserved</b>	-	-	-	-
PosSTW1.14	<b>Reserved</b>	-	-	-	-
PosSTW1.15	<b>Reserved</b>	-	-	-	-

&lt;1&gt; Used in telegram 110, 999.

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DO: SERVO, VECTOR

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Function diagram

PROFIdrive - PosSTW Pos Control Word interconnection (r0108.4 = 1)

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