

| Signal sources for ZSW1 in Interface Mode VIK-NAMUR (p2038 = 2) |   |                            |  |                                     |                 | <1> |
|---|---|----------------------------|--|-------------------------------------|-----------------|-----|
| Signal  | Meaning   | Interconnection parameters | [Function diagram]<br>Internal status word | [Function diagram]<br>Signal source | Inverted<br><2> |     |
| ZSW1.0  | <b>1 = Ready to power-up</b>  | p2080[0] = r0899.0         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.1  | <b>1 = Ready to operate (DC link loaded, pulses blocked)</b>  | p2080[1] = r0899.1         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.2  | <b>1 = Operation enabled (drive follows n_set)</b>  | p2080[2] = r0899.2         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.3  | <b>1 = Fault present</b>  | p2080[3] = r2139.3         | [2548.7]                                   | [8060]                              | -               |     |
| ZSW1.4  | <b>1 = No coast down active (OFF2 inactive)</b>   | p2080[4] = r0899.4         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.5  | <b>1 = No fast stop active (OFF3 inactive)</b>  | p2080[5] = r0899.5         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.6  | <b>1 = Power-on inhibit active</b>  | p2080[6] = r0899.6         | [2503.7]                                   | [2610]                              | -               |     |
| ZSW1.7  | <b>1 = Alarm present</b>  | p2080[7] = r2139.7         | [2548.7]                                   | [8065]                              | -               |     |
| ZSW1.8  | <b>1 = Speed setpoint - actual value deviation within tolerance t_off</b>   | p2080[8] = r2197.7         | [2534.7]                                   | [8010]                              | -               |     |
| ZSW1.9  | <b>1 = Control requested</b> <3>  | p2080[9] = r0899.9         | [2503.7]                                   | [2503]                              | -               |     |
| ZSW1.10   | <b>1 = f or n comparison value reached/exceeded</b>   | p2080[10] = r2199.1        | [2536.7]                                   | [8010]                              | -               |     |
| ZSW1.11   | <b>1 = I, M, or P limit not reached</b>   | p2080[11] = r0056.13       | [2522.7]                                   | [6060]                              | ✓               |     |
| ZSW1.12   | <b>Reserved</b>   | -                          | -  | -                                   | -               |     |
| ZSW1.13   | <b>1 = No motor overtemperature alarm</b>   | p2080[13] = r2135.14       | [2548.7]                                   | [8016]                              | ✓               |     |
| ZSW1.14   | <b>1 = Motor rotates forwards (<math>n_{act} \geq 0</math>)<br/>0 = Motor rotates backwards (<math>n_{act} &lt; 0</math>)</b> | p2080[14] = r2197.3        | [2534.7]                                   | [8010]                              | -               |     |
| ZSW1.15   | <b>1 = Display CDS</b>  | p2080[15] = r0836.0        | -  | -                                   | -               |     |

&lt;1&gt; Used in telegram 20.

&lt;2&gt; The ZSW1 is generated using the binector-connector converter (BI: p2080[0...15], inversion: p2088[0].0...p2088[0].15)

&lt;3&gt; The master system requests the process data.

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DO: VECTOR

fp\_2451\_01\_eng.vsd

Function diagram

- 2451 -

PROFIdrive - ZSW1 status word interconnection (p2038 = 2)

17.04.07 V02.05.00

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