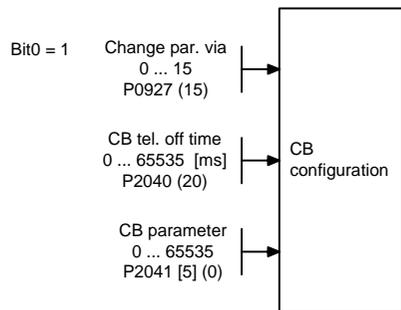


- Bit00 ON/OFF1
- Bit01 OFF2: Electrical stop
- Bit02 OFF3: Fast stop
- Bit03 Pulse enable
- Bit04 RFG enable
- Bit05 RFG start
- Bit06 Setpoint enable
- Bit07 Fault acknowledge
- Bit08 JOG right
- Bit09 JOG left
- Bit10 Control from PLC
- Bit11 Reverse (setpoint inversion)
- Bit13 Motor potentiometer MOP up
- Bit14 Motor potentiometer MOP down
- Bit15 CDS Bit 0 (Local/Remote)

- Bit00 Fixed frequency Bit 0
- Bit01 Fixed frequency Bit 1
- Bit02 Fixed frequency Bit 2
- Bit03 Fixed frequency Bit 3
- Bit04 Drive data set (DDS) Bit 0
- Bit05 Drive data set (DDS) Bit 1
- Bit08 PID enabled
- Bit09 DC brake enabled
- Bit11 Droop
- Bit12 Torque control
- Bit13 External fault 1
- Bit15 Command data set (CDS) Bit 1



Note:
 Bit 10 must be set in the first PZD word of the telegram received via USS so that the converter will accept the process data as being valid. For this reason, the control word 1 must be transferred to the converter in the first PZD word.

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External Interfaces					2700_CBoNCOM.vsd	Function diagram	
CB on COM link, Receiving					16.08.2006 V2.1	MICROMASTER 430	