

Bit00 Drive ready
 Bit01 Drive ready to run
 Bit02 Drive running
 Bit03 Drive fault active
 Bit04 OFF2 active
 Bit05 OFF3 active
 Bit06 ON inhibit active
 Bit07 Drive warning active
 Bit08 Deviation setpoint / act. value
 Bit09 PZD control
 Bit10 Maximum frequency reached
 Bit11 Warning: Motor current limit
 Bit12 Motor holding brake active
 Bit13 Motor overload
 Bit14 Motor runs right
 Bit15 Inverter overload

Bit00 DC brake active
 Bit01 Act. freq. r0021 > P2167 (f_off)
 Bit02 Act. freq. r0021 > P1080 (f_min)
 Bit03 Act. current r0027 >= P2170
 Bit04 Act. freq. r0021 >= P2155 (f_1)
 Bit05 Act. freq. r0021 < P2155 (f_1)
 Bit06 Act. freq. r0021 >= setpoint
 Bit07 Act. Vdc r0026 < P2172
 Bit08 Act. Vdc r0026 > P2172
 Bit09 Ramping finished
 Bit10 PID output r2294 == P2292 (PID_min)
 Bit11 PID output r2294 == P2291 (PID_max)
 Bit14 Download data set 0 from AOP
 Bit15 Download data set 1 from AOP

CO/BO: Act StatWd1

r0052
r0052

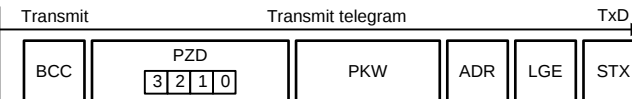
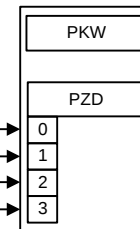
CO: Act. frequency [Hz]

r0021

CO/BO: Act StatWd2

r0053
r0053

Note:
 P2016[0] = 52
 P2016[1] = 21
 P2016[3] = 53
 are default settings



Bit2 = 1

All parameters:
 Index = 1
 => BOP link

Change par. via
 0 ... 15
 P0927 (15)

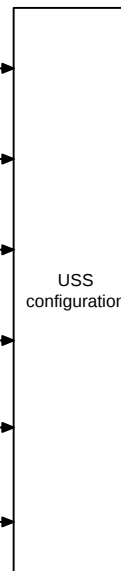
USS baudrate
 3 ... 9
 P2010 [2] (6)

USS address
 0 ... 31
 P2011 [2] (0)

USS PZD length
 0 ... 4
 P2012 [2] (2)

USS PKW length
 0 ... 127
 P2013 [2] (127)

USS telegram T_off
 0 ... 65535 [ms]
 P2014 [2] (0)



1	2	3	4	5	6	7	8
External Interfaces					2510_USSonBOP.vsd	Function diagram	- 2510 -
USS on BOP link, Transmitting					16.08.2006 V1.2	MICROMASTER 420	