ABB Inc.

HARD TO FIND INFORMATION ABOUT DISTRIBUTION SYSTEMS

Reference Material

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James Burke Executive Consultant Phone: (919) 856-3311 Fax: (919) 807-5060 jim.j.burke@us.abb.com distjimb@aol.com

ABB Inc. Consulting 940 Main Campus Drive Raleigh, NC 27606

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Legal Notice

Jim Burke is an Institute Fellow at ABB and a recognized expert on power distribution systems. He has authored over 70 technical papers in the field, including two prize papers, as well as the book *Power Distribution Systems, Fundamentals and Application.* This document is a cumulative effort developed by Jim Burke spanning over thirty years of teaching. ABB makes no warranty and assumes no liability with respect to the accuracy, suitability or usefulness of the information contained within.



I. Preface

There have been little tidbits of information I have accumulated over the years that have helped me understand and analyze distribution systems. I have pinned them to my wall, taped them to my computer, stuffed them in my wallet and alas, copied them for my students. Much of them are hard, if not impossible, to find in any reference book. A large percentage of them could also be classified as personal opinion so they should be used carefully. For whatever, I hope they are as useful to you as they have been to me.

II. System Characteristics and Protection

A. Introduction

The distribution system shown below illustrates many of the features of a distribution system making it unique. The voltage level of a distribution system can be anywhere from about 5 kV to as high as 35 kV with the most common voltages in the 15 kV class. Areas served by a given voltage are proportional to the voltage itself indicating that, for the same load density, a 35 kV system can serve considerably longer lines. Lines can be as short as a mile or two and as long as 20 or 30 miles. Typically, however, lines are generally 10 miles or less. Short circuit levels at the substation are dependent on voltage level and substation size. The average short circuit level at a distribution substation has been shown, by survey, to be about 10,000 amperes. Feeder load current levels can be as high as 600 amperes but rarely exceed about 400 amperes with many never exceeding a couple of hundred amperes. Underground laterals are generally designed for 200 amperes of loading but rarely approach even half that value. A typical lateral load current is probably 50 amperes or less even during cold load pickup conditions.

B. Fault Levels

There are two types of faults, low impedance and high impedance. A high impedance fault is considered to be a fault that has a high Z due to the contact of the conductor to the earth, i.e., Z_f is high. By this definition, a bolted fault at the end of a feeder is still classified as a low impedance fault. A summary of findings on faults and their effects is as follows:



Figure 1. Typical distribution system

C. Low Impedance Faults

Low impedance faults or bolted faults can be either very high in current magnitude (10,000 amperes or above) or fairly low, e.g., 300 amperes at the end of a long feeder. Faults able to be detected by normal protective devices are all low impedance faults. These faults are such that the calculated value of fault current assuming a "bolted fault" and the actual are very similar. Most detectable faults, per study data, do indeed show that fault impedance is close to 0 ohms. This implies that the phase conductor either contacts the neutral wire or that the arc to the neutral conductor has a very low impedance. An EPRI study performed by the author over 10 years ago indicated that the maximum fault impedance for a detectable fault was 2 ohms or less. Figure 2, shown below, indicates that 2 ohms of fault impedance influences the level of fault current depending on location of the fault. As can be seen, 2 ohms of fault impedance considerably decreases the level of fault current for close in faults but has little effect for faults some distance away. What can be concluded is that *fault impedance does not significantly affect faulted circuit indicator performance* since low level faults are not greatly altered.



FAULT LEVEL vs. DISTANCE

Figure 2. Low impedance faults

D. High Impedance Faults

High impedance faults are faults that are low in value, i.e., generally less than 100 amperes due to the impedance between the phase conductor and the surface on which the conductor falls. Figure 3, shown below, illustrates that most surface areas whether wet or dry do not conduct well. If one considers the fact that an 8 foot ground rod sunk into the earth more often than not results in an impedance of 100 ohms or greater, then it is not hard to visualize the fact that a conductor simply lying on a surface cannot be expected to have a low impedance. These faults, called high impedance faults, do not contact the neutral and do not arc to the neutral. They are not detectable by any conventional means and are not to be considered at all in the evaluation of FCIs and most other protective devices.

E. Surface Current Levels



Figure 3. High impedance fault current levels

F. Reclosing and Inrush

On most systems where most faults are temporary, the concept of reclosing and the resulting inrush currents are a fact of life. Typical reclosing cycles for breakers and reclosers are different and are shown below in Figure 4.



Feeder Breaker Reclosing

Figure 4. Reclosing sequences

These reclosing sequences produce inrush primarily resulting from the connected transformer kVA. This inrush current is high and can approach the actual fault current level in many instances. Figure 5 shows the relative magnitude of these currents. What keeps most protective devices from operating is that the duration of the inrush is generally short and as a consequence will not melt a fuse or operate a time delay relay.

G. Cold Load Pickup

Cold load pickup, occurring as the result of a permanent fault and long outage, is often maligned as the cause of many protective device misoperations. Figure 6, shown below, illustrates several cold load pickup curves developed by various sources. These curves are normally considered to be composed of the following three components:



Figure 5. Magnitudes of inrush current

- 1) Inrush lasting a few cycles
- 2) Motor starting lasting a few seconds
- 3) Loss of diversity lasting many minutes.

When a lateral fuse misoperates, it is probably not the result of this loss of diversity, i.e., the fuse is overloaded. This condition is rare on most laterals. Relay operation during cold load pickup is generally the result of a trip of the instantaneous unit and probably results from high inrush. Likewise, an FCI operation would not appear to be the result of loss of diversity but rather the high inrush currents. Since inrush occurs during all energization and not just as a result of cold load pickup, it can be concluded that cold load pickup is not a major factor in the application of FCIs.



Figure 6. Cold-load inrush current characteristics for distribution circuits

H. Calculation of Fault Current

Line Faults Line-to-neutral fault =

$$\sqrt{3} \bullet 2 \bullet \mathbf{Z}_{\lambda}$$

E

Where Z_t is the line impedance and $2Z_t$ is the loop impedance assuming the impedance of the phase conductor and the neutral conductor are equal (some people use a 1.5 factor).

Line-to-Line Faults =

$$\overline{2Z_{\lambda}}$$

E

<u>Transformer Faults</u> Line-to-neutral or three phase =

$$\frac{\mathrm{E}}{\sqrt{3} \bullet \mathrm{Z}_{\mathrm{T}}}$$

$$\frac{E}{2(Z_{T} + Z_{\lambda})} \quad \text{where} \quad Z_{\lambda} = \sqrt{R_{L}^{2} + X_{L}^{2}}$$
$$Z_{T} = \frac{Z_{T\%} \bullet 10 \bullet E^{2}}{kVA}$$

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I. Rules for Application of Fuses

- 1) Cold load pickup after 15 minute outage, 200% for 5 seconds 140% for 5 seconds after 4 hrs, all electric 300% for 5 minutes
- 2) "Damage" curve 75% of minimum melt
- **3)** Two expulsion fuses cannot be coordinated if the available fault current is great enough to indicate an interruption of less than .8 cycles.
- 4) "T" SLOW and "K" FAST
- 5) Current limiting fuses can be coordinated in the sub-cycle region.
- 6) Capacitor protection:
 - The fuse should be rated for 165% of the normal capacitor current. The fuse should also clear within 300 seconds for the minimum short circuit current.
 - If current exceeds the maximum case rupture point, a current limiting fuse must be used.
 - Current limiting fuses should be used if a single parallel group exceeds 300 KVAR.
- 7) Transformer
 - Inrush 12 times for .1 sec.
 - 25 times for .01 sec.
 - Self protected primary fuse rating is 10 to 14 times continuous when secondary breaker is used.
 - Self protected weak link is selected to be about 2 1/2 times the continuous when no secondary breaker is used (which means that minimum melt is in the area of 4 to 6 times rating).
 - Conventional primary fuse rated 2 to 3 times.
 - General Purpose current limiting 2 to 3 times continuous.
 - Back-Up current limiting the expulsion and CLF are usually coordinated such that the minimum melt I²t of the expulsion fuse is equal to or less than that of the back up CLF.
- 8) Conductor burn down not as great a problem today because loads are higher and hence conductors are larger.
- 9) General purpose one which will successfully clear any current from its rated maximum interrupting current down to the current that will cause melting of the fusible element in one hour.
- **10)** Back up one which will successfully clear any current from its rated maximum interrupting down to the rated minimum interrupting current, which may be at the 10 second time period on the minimum melting time-current curve.
- 11) CLF approximately 1/4 cycle operation; can limit energy by as much as 60 to 1.

- 12) Weak link in oil is limited to between 1500 and 3500 amperes.
- **13)** Weak link in cutout is limited to 6000 to 15000 asymmetrical.
- **14)** Lightning minimum fuse (12T-SLOW), (25K-FAST).
- **15)** Energy stored in inductance = $\frac{1}{2}$ Li²
- **16)** The maximum voltage produced by a C.L. fuse typically will not exceed 3.1 times the fuse rated maximum voltage.
- **17)** The minimum sparkover allowed for a gapped arrester is 1.5 x 1.414 = 2.1 times arrester rating.
- **18)** General practice is to keep the minimum sparkover of a gapped arrester at about 2.65 x arrester rating.
- **19)** MOVs do not have a problem with CLF "kick voltages."

J. Capacitor Fusing

1) Purpose of fusing:

- a. to isolate faulted bank from system
- b. to protect against bursting
- c. to give indication
- d. to allow manual switching (fuse control)
- e. to isolate faulted capacitor from bank

2) Recommended rating:

- a. The continuous-current capability of the fuse should be at least 165 percent of the normal capacitor-bank (for delta and floating wye banks the factor may be reduced to 150 percent if necessary).
- b. The total clearing characteristics of the fuse link must be coordinated with the capacitor "case bursting" curves.
- **3)** Tests have shown that expulsion fuse links will not satisfactorily protect against violent rupture where the fault current through the capacitor is greater than 5000 amperes.
- 4) The capacitor bank may be connected in a floating wye to limit short-circuit current to less than 5000 amperes.
- 5) **Inrush** for a single bank, the inrush current is always less than the short-circuit value at the bank location.
- 6) Inrush for parallel banks, the inrush current is always much greater than for a single bank.
- 7) **Expulsion fuses** offer the following advantages:
 - a. they are inexpensive and easily replaced.
 - b. offers a positive indication of operation.



- 8) Current limiting fuses are used where:
 - a. a high available short circuit exceeds the expulsion or non-vented fuse rating.
 - b. a current limiting fuse is needed to limit the high energy discharge from adjacent parallel capacitors effectively.
 - c. a non-venting fuse is needed in an enclosure.
- 9) The fuse link rating should be such that the link will melt in 300 seconds at 240 to 350 percent of normal load current.
- **10)** The fuse link rating should be such that it melts in one second at not over 220 amperes and in .015 seconds at not over 1700 amperes.
- **11)** The fuse rating must be chosen through the use of melting time-current characteristics curves, because fuse links of the same rating, but of different types and makes have a wide variation in the melting time at 300 seconds and at high currents.
- **12)** Safe zone usually greater damage than a slight swelling.
 - a. <u>Zone 1</u> suitable for locations where case rupture/or fluid leakage would present no hazard.
 - b. <u>Zone 2</u> suitable for locations which have been chosen after careful consideration of possible consequences associated with violent case ruptures.
 - c. <u>Hazardous zone</u> unsafe for most applications. The case will often rupture with sufficient violence to damage adjacent units.
- **13)** Manufacturers normally recommend that the group fuse size be limited by the 50% probability curve or the upper boundary of Zone 1.
- **14)** Short circuit current in an open wye bank is limited to approximately 3 times normal current.
- **15)** Current limiting fuses can be used for delta or grounded wye banks provided there is sufficient short circuit current to melt the fuse within ½ cycle.

K. Conductor Burndown

Conductor burndown is a function of (1) conductor size (2) whether the wire is bare or covered (3) the magnitude of the fault current (4) climatic conditions such as wind and (5) the duration of the fault current.

If burndown is less of a problem today than in years past it must be attributed to the trend of using heavier conductors and a lesser use of covered conductors. However, extensive outages and hazards to life and property still occur as the result of primary lines being burned down by flashover, tree branches failing on lines, etc. Insulated conductors, which are used less and less, anchor the arc at one point and thus are the most susceptible to being burned down. With bare conductors, except on multi-grounded neutral circuits, the motoring action of the current flux of an arc always tends to propel the arc along the line away from the power source until the arc elongates sufficiently to automatically extinguish itself. However, if the arc encounters some insulated object, the arc will stop traveling and may cause line burndown.

With tree branches falling on bare conductors, the arc may travel away and clear itself; however, the arc will generally re-establish itself at the original point and continue this procedure until the line burns down or the branch falls off the line. Limbs of soft spongy wood are more likely to burn clear than hard wood.



However one-half inch diameter branches of any wood, which cause a flashover, are apt to burn the lines down unless the fault is cleared quickly enough.

Figure 7 shows the burndown characteristics of several weatherproof conductors. Arc damage curves are given as arc is extended by traveling along the phase wire, it is extinguished but may be re-established across the original path. Generally, the neutral wire is burned down.



Figure 7. Burndown characteristics of several weatherproof conductors

L. Device Numbers

The devices in the switching equipment are referred to by numbers, with appropriate suffix letters (when necessary), according to the functions they perform. These numbers are based on a system which has been adopted as standard for automatic switchgear by the American Standards Association.

Table 1

Device No.	Function and Definition
11	CONTROL POWER TRANSFORMER is a transformer which serves as the source of a-c control power for operating a-c devices.
24	BUS-TIE CIRCUIT BREAKER serves to connect buses or bus sections together.
27	A-C UNDERVOLTAGE RELAY is one which functions on a given value of single-phase a-c under voltage.
43	TRANSFER DEVICE is a manually operated device which transfers the control circuit to modify the plan of operation of the switching equipment or of some of the devices.
50	SHORT-CIRCUIT SELECTIVE RELAY is one which function instantaneously on an excessive value of current.
51	A-C OVERCURRENT RELAY (inverse time) is one which functions when the current in an a-c circuit exceeds a given value.
52	A-C CIRCUIT BREAKER is one whose principal function is usually to interrupt short-circuit or fault currents.
64	GROUND PROTECTIVE RELAY is one which functions on failure of the insulation of a machine, transformer or other apparatus to ground. This function is, however, not applied to devices 51N and 67N connected in the residual or secondary neutral circuit of current transformers.
67	A-C POWER DIRECTIONAL OR A-C POWER DIRECTIONAL OVERCURRENT RELAY is one which functions on a desired value of power flow in a given direction or on a desired value of overcurrent with a-c power flow in a given direction.
78	PHASE-ANGLE MEASURING RELAY is one which functions at a predetermined phase angle between voltage and current.
87	DIFFERENTIAL CURRENT RELAY is a fault-detecting relay which functions on a differential current of a given percentage or amount.

M. Protection Abbreviations

CS -Control Switch

X - Auxiliary Relay

Y - Auxiliary Relay

YY - Auxiliary Relay

Z - Auxiliary Relay

1) To denote the location of the main device in the circuit or the type of circuit in which the device is used or with which it is associated, or otherwise identify its application in the circuit or equipment, the following are used:



N – Neutral SI - Seal-in

2) To denote parts of the main device (except auxiliary contacts as covered under below), the following are used:

H - High set unit of relay L - Low set unit of relay OC - Operating coil RC - Restraining coil TC - Trip coil

3) To denote parts of the main device such as auxiliary contacts (except limit-switch contacts covered under 3 above) which move as part of the main device and are not actuated by external means. These auxiliary switches are designated as follows:

"a" - closed when main device is in energized or operated position

- "b" closed when main device is in de-energized or non-operated position.
- 4) To indicate special features, characteristics, the conditions when the contacts operate, or are made operative or placed in the circuit, the following are used:

A-	Automatic
ER-	Electrically Reset
HR-	Hand Rest
M-	Manual
TDC-	Time-delay Closing
TDDO-	Time-delay Dropping Out
TDO-	Time-delay Opening

To prevent any possible conflict, one letter or combination of letters has only one meaning on an individual equipment. Any other words beginning with the same letter are written out in full each time, or some other distinctive abbreviation is used.

N. Simple Coordination Rules



Figure 8. "Burke 2X rule"

There are few things more confusing in distribution engineering than trying to find out rules of overcurrent coordination, i.e., what size fuse to pick or where to set a relay, etc. The patented (*just kidding*) Burke 2X Rule states that when in doubt pick a device of twice the rating of what it is you're trying to protect as shown in Figure 8. This rule picks the minimum value you should normally consider and is generally as good as any of the much more complicated approaches you might see. For various reasons, you might want to go higher than this, which is usually OK. To go lower, you will generally get into trouble. Once exception to this rule is the fusing of capacitors where minimum size fusing is important to prevent case rupture.

O. Lightning Characteristics

- 1) Stroke currents
 - a. Maximum 220,000 amperes
 - b. Minimum 200 amperes
 - c. Average-10,000 to 15,000 amperes
- 2) Rise times 1 to 100 microseconds
- 3) Lightning polarity approximately 95% are negative
- 4) Annual variability (Empire State Building)

a.	Maximum number of hits	50
----	------------------------	----

о.	Average	21
о.	Average	2

c. Minimum 3

(8-year measurement period)

- 5) Direct strokes to T line 1 per mile per year with keraunic levels between 30 and 65.
- 6) Lightning discharge currents in distribution arresters on primary distribution lines (composite of urban and rural)

approx.	40,000 amps
	22,000 amps
	10,500 amps
	6,000 amps
	1,500 amps
	approx.

7) Percent of distribution arresters receiving lightning currents at least as high as in Col. 4.

Col. 1 Urban Circuits	Col. 2 Semi-urban Circuits	Col. 3 Rural Circuits	Col. 4 Discharge Circuits
20%	35%	45%	1,000 amps
1.6%	7%	12%	5,000 amps
.55%	3.5%	6%	10,000 amps
.12%	.9%	2.4%	20,000 amps
		.4%	40,000 amps

Table 2

8) Number of distribution arrester operations per year (excluding repeated operations on multiple strokes).

Average on different systems - range	.5 to 1.1 per year
Max. recorded	6 per year
Max. number of successive	
operations of one arrester	
during one multiple lightning	
stroke -	12 operations.

P. Arc Impedence

While arcs are quite variable, a commonly accepted value for currents between 70 and 20,000 amperes has been an arc drop of 440V per foot, essentially independent of current magnitude.

$$Z_{arc} = 440 //I$$
 / = length of arc (in feet) I = current

Assume:

 $I_F = 500 \text{ amperes} = I$

Arc length = 2 ft.

 Z_{arc} = 440 • 2/5000 = .176 ohms \therefore Arc impedance is pretty small.



III. Transformers

A. Saturation Curve





B. Insulation Levels

The following table gives the American standard test levels for insulation of distribution transformers.

Table	3
-------	---

		Windings		Bushings			
		Impulse Tests (1.2 x 50 Wave)		Bushing Withstand Voltages		Voltages	
		CI	nopped Wave				
Insulation Class and Nominal Bushing Rating	Low- frequency Dielectric Tests	Mir	nimum Time to Flashover	Full Wave	60-cycle One- minute Dry	60-cycle 10- second Wet	Impulse 1.2 x 50 Wave
kV	kV	kV	Microseconds	kV	kV (Rms)	kV (Rms)	kV (Crest)
1.2	10	36	1.0	10	10	6	30
5.0	19	69	1.5	60	21	20	60
8.66	26	88	1.6	75	27	24	75
15.0	34	110	1.8	95	35	30	95
25.0	40	145	1.9	125	70	60	150
34.5	70	175	3.0	150	95	95	200
46.0	95	290	3.0	250	120	120	250
69.0	140	400	3.0	350	175	175	350

C. Δ -Y Transformer Banks

The following is a review of fault current magnitudes for various secondary faults on a Δ -Y transformer bank connection:



Figure 10. Δ -Y transformer banks

D. Transformer Loading

When the transformer is overloaded, the high temperature decreases the mechanical strength and increases the brittleness of the fibrous insulation. Even though the insulation strength of the unit may not be seriously decreased, transformer failure rate increases due to this mechanical brittleness.

- Insulation life of the transformer is where it loses 50% of its tensile strength. A transformer may continue beyond its predicted life if it is not disturbed by short circuit forces, etc.
- The temperature of top oil should never exceed 100 degrees C for power transformers with a 55 degree average winding rise insulation system. Oil overflow or excessive pressure could result.
- The temperature of top oil should not exceed 110C for those with a 65C average winding rise.
- Hot spot should not exceed 150C for 55C systems and 180C for 65C systems. Exceeding these temperature could result in free bubbles that could weaken dielectric strength.
- Peak short duration loading should never exceed 200%.
- Standards recommend that the transformer should be operated for normal life expectancy. In the event of an emergency, a 2.5% loss of life per day for a transformer may be acceptable.



• Percent Daily Load for Normal Life Expectancy with 30°C Cooling Air

Duration of Peak load	Self-cooled with % load before peak of:			
Hours	50%	70%	90%	
0.5	189	178	164	
1	158	149	139	
2	137	132	124	
4	119	117	113	
8	108	107	106	

Table 4

IV. Instrument Transformers

A. Two Types

- 1) Potential (Usually 120v secondary)
- 2) Current (5 amps secondary at rated primary current)

B. Accuracy

3 factors will influence accuracy:

- 1) Design and construction of transducer
- 2) Circuit conditions (V, I and f)
- 3) Burden (in general, the higher the burden, the greater the error)

C. Potential Transformers





Voltage at secondary is low and must be compensated by 11% to get the actual primary voltage using the marked ratio.

D. Current Transformer

∴RCF = <u>True Ratio</u> Marked Ratio

E. H-Class



Burdens are in series

```
e.g. 10H200 \Rightarrow 10% error @ 200V
```

 \therefore 20 (5 amp sec) = 100 amps \Rightarrow Z_b = 200/100 = 2 Ω

 \Rightarrow 5 amps to 100 amps has \leq 10% error if Z_{b} = 4 Ω OR If Z_{b} = 4 Ω

 $200V/4\Omega$ = 50 amp (10 times normal)

H-class – constant magnitude error (variable %) L-class – constant % error (variable magnitude)

Example:

True Ratio = Marked Ratio X RCF

Assume Marked is 600/5 or 120:1 at rated amps and 2 ohms



1.002 and 1.003 are from manuf. chart

@ 100% amps True = 120 X 1.002 X 5 secondary primary = 600 X 1.002 = 601.2

@ 20% amps True = 600 X .2 X 1.003 = 120.36 (Marked was 120)

F. Current Transformer Facts

- **1)** Bushing CTs tend to be accurate more on high currents (due to large core and less saturation) than other types.
- 2) At low currents, BCT's are less accurate due to their larger exciting currents.

2

- 3) Rarely, if ever, is it necessary to determine the phase-angle error.
- 4) Accuracy calculations need to be made <u>only</u> for three-phase and single-phase to ground faults.

- 5) CT burden decreases as secondary current increases, because of saturation in the magnetic circuits of relays and other devices. At high saturation, the impedance approaches the dc resistance.
- 6) It is usually sufficiently accurate to add series burden impedance arithmetically.
- 7) The reactance of a tapped coil varies as the square of the coil turns, and the resistance varies approximately as the turns.
- 8) Impedance varies as the square of the pickup current.
- 9) Burden impedance are always connected in wye.
- **10)** "Ratio correction factor" is defined as that factor by which the marked ratio of a current transformer must be multiplied to obtain the true ratio. These curves are considered standard application data.
- **11)** The secondary-excitation-curve method of accuracy determination does not lend itself to general use except for bushing-type, or other, CT's with completely distributed secondary leakage, for which the secondary leakage reactance is so small that it may be assumed to be zero.
- **12)** The curve of rms terminal voltage versus rms secondary current is approximately the secondary-excitation curve for the test frequency.
- **13)** ASA Accuracy Classification:
 - a. Method assumes CT is supplying 20 times its rated secondary current to its burden.
 - b. The CT is classified on the basis of the maximum rms value of voltage that it can maintain at its secondary terminals without its ratio error exceeding a specified amount.
 - c. "H" stands for high internal secondary impedance.
 - d. "L" stands for low internal secondary impedance (bushing type).
 - e. 10H800 means the ratio error is 10% at 20 times rated voltage with a maximum secondary voltage of 800 and high internal secondary impedance.
 - f. Burden (max) maximum specified voltage/20 x rated sec.
 - g. The higher the number after the letter, the better the CT.
 - h. A given I200/5 busing CT with 240 secondary turns is classified as I0L400: if a 120-turn completely distributed tap is used, then the applicable classification is 10L200.
 - i. For the same voltage and error classifications, the H transformer is better than the L for currents up to 20 times rated.

G. Glossary of Transducer Terms

Voltage Transformers - are used whenever the line voltage exceeds 480 volts or whatever lower voltage may be established by the user as a safe voltage limit. They are usually rated on a basis of 120 volts secondary voltage and used to reduce primary voltage to usable levels for transformer-rated meters.

Current Transformer - usually rated on a basis of 5 amperes secondary current and used to reduce primary current to usable levels for transformer-rated meters and to insulate and isolate meters from high voltage circuits.

Current Transformer Ratio - ratio of primary to secondary current. For current transformer rated 200:5, ratio is 200:5 or 40: 1.

Voltage Transformer Ratio - ratio of primary to secondary voltage. For voltage transformer rated 480:120, ratio is 4:1, 7200:120 or 60:1.

Transformer Ratio (TR) - total ratio of current and voltage transformers. For 200:5 C.T. and 480:120 P.T., TR = $40 \times 4 = 160$.

Weatherability - transformers are rated as indoor or outdoor, depending on construction (including hardware).

Accuracy Classification - accuracy of an instrument transformer at specified burdens. The number used to indicate accuracy is the maximum allowable error of the transformer for specified burdens. For example, 0.3 accuracy class means the maximum error will not exceed 0.3% at stated burdens.

Rated Burden - the load which may be imposed on the transformer secondaries by associated meter coils, leads and other connected devices without causing an error greater than the stated accuracy classification.

Current Transformer Burdens - normally expressed in ohms impedance such as B0.1,B-0.2,B-0.5,B-0.9,or B-1.8.Corresponding volt-ampere values are 2.5, 5.0, 12.5, 22.5, and 45.

Voltage Transformer Burdens - normally expressed as volt-amperes at a designated power factor. May be W, **X**, M, Y, or Z where W is 12.5 V.A. @ 0. 1Opf; X is 25 V.A. @ 0.70pf, M is 35 V.A. @ 0.20 pf, Y is 75 V.A. @ 0.85pf and Z is 200 V.A. @0.85 pf. The complete expression for a current transformer accuracy classification might be 0.3 at BO. 1, B-0.2, and B-0. 5, while the potential transformer might be 0.3 at W, X, M, and Y.

Continuous Thermal Rating Factor (TRF) - normally designated for current transformers and is the factor by which the rated primary current is multiplied to obtain the maximum allowable primary current without exceeding temperature rise standards and accuracy requirements. Example - if a 400:5 CT has a TRF of 4.0, the CT will continuously accept 400 x 4 or 1600 primary amperes with 5 x 4 or 20 amperes from the secondary. The thermal burden rating of a voltage transformer shall be specified in terms of the maximum burden in volt-amperes that the transformer can carry at rated secondary voltage without exceeding a given temperature rise.

Rated Insulation Class - denotes the nominal (line-to-line) voltage of the circuit on which it should be used. Associated Engineering Company has transformers rated for 600 volts through 138 kV.

Polarity - the relative polarity of the primary and secondary windings of a current transformer is indicated by polarity marks (usually white circles), associated with one end of each winding. When current enters at the polarity end of the primary winding, a current in phase with it leaves the polarity end of the secondary winding. Representation of primary marks on wiring diagrams are shown as black squares.



Hazardous Open-Circulating - operation of CTs with the secondary winding open can result in a high voltage across the secondary terminals which may be dangerous to personnel or equipment. Therefore, the secondary terminals should always be short circuited before a meter is removed from service. This may be done automatically with a by-pass in the socket or by a test switch for A-base meters.

V. Rules of Thumb for Uniformly Distributed Loads

It is very helpful to be able to perform a quick sanity check of system conditions "usually in your head" to develop a "feel" for whether there might be a problem. Three very helpful rules assuming a uniformly distributed load are as follows:

1) Capacitor placement - "2/3 rule"



Figure 11. Optimum capacitor placement

"Optimum placement of capacitors at 2/3 the distance of the line, sizing the bank to meet 2/3 of the feeder VAR needs."

2) Losses - "1/3 rule"



Figure 12. Equivalent losses

"Place all the load at 1/3 the distance to obtain the same losses as an evenly distributed load."

3) Voltage drop - "1/2 rule"



Figure 13. Equivalent voltage drop

"Place 100% of load at 1/2 point on the feeder to obtain the same voltage drop as the voltage at the end of the feeder for a uniform distribution load."

VI. Conductors and Cables

A. Conductor Current Rating

Table 5

Wire Size	Amps
6	55
4	75
2	105
1/0	145
2/0	170
3/0	200
4/0	240
336	330
397	370
565	480
795	620

B. Facts on Distribution Cable

- 1) Cable replacement occurs usually after 2 or 3 failures.
- 2) TRXLPE and EPR use is increasing.
- 3) Conduit is on the rise but most cable is direct buried.
- 4) About 60% of all cable is still going in direct buried.
- 5) Most common method to find fault is radar with a thumper, followed by a thumper by itself then an FCI.
- 6) Most utilities use an insulating jacket type, followed by the use of the semi-conducting jacket.
- 7) 30% use fiber optics in the underground system for telephone, SCADA, computer-tocomputer, video, etc.
- 8) Jacketed EPR has good record.
- 9) HMWPE and non-jacketed XLPE have bad records.

C. Impedance of Cable

Impedance of the main feeder is:

- 1) .122 + j .175 ohms/mile (12kV, 1000 KCM)
- 2) .119 + j .190 ohms/mile (35kV, 1000 KCM)

Impedance of the lateral feed is:

- 1) .502 + j .211 ohm/mile (12kV, 4/0, 3Ø)
- 2) .500 + j .238 ohm/mile (34kV, 4/0, 3Ø)
- 3) 1.445 + j .552 ohms/mile (12kV, #4, 1Ø)
- 4) 1.607 + j .595 ohms/mile (34kV, #4, 1Ø)

Table 6				
Impadance Table (R and X) For Commonly Used Wire and Cable				
			Resetance per	Rescance per
Wine Stee	Туря	Bpacing	1000 Ft	1006 PL
335 ACSR	Open Wite	14	0.368	0 128
i H	Open Ware	1 S FI	0 262	u 125
a ?	Open Wire	: 5 FI	0.163	0150
#0. 1 0	Open Wire	: 5 FL	Q 105	C 10
#2.0	Open Wite	15 FI	0.063	C 10
M 0	Open Wite	1 S FI	0.253	0.005
# 5	Open Wire	OCFI.	04'3	E 146
24	Open Wire	3 C FI	0.262	C 141
12	Open Wra	3 C FI	3 IB I	0.143
¢.0	Open Witte	<u> </u>	0.105	0.125
120	Open Wite	3 G FI	0.0S1	0.136
#10	Open Wire	3.C FI.	3 025	0.121
12	Self Supp	Cable	0.162	0.062
420	Self Supp.	Cable	0.084	0.046
14 /0	Self Supp.	Calle	0.053	0053
0.0	PAL	Cattle	0.059	0.036
350 MCM	P AL	Cable	0.036	0.038
¥'.C	Source	35 M	0.168	0.075
#40G	Spacer	35 M.	0.084	0.067
1 10	Scecer	536	0.168	0 366
MC	Scene	50 km	0.054	0.079
17) Alum	Doen Wre	3.0 Pt	0 :68	0 (29
AGI Alur-	Coso Whe	3.0 Ft	0.092	0 12\$
367 Alur	Open Wire	30P;	0.045	D1'3
1.0 AL	Coen Wire	1.5 P	0,26	U 112
30 Ab.m	Cren W/+	1 5 F1	G C84	0.106
"357 Alum ASCP	Open Wife	15 PI	0.045	0.095
397 Alum	Open Wire	1 D Fi	E 644	0.087
3-16 500 MCV	Network		0.024	0.032
'Amless Constructory				

VII. DSG – General Requirements

- 1) Voltage Customer shall not cause voltage excursions. Any voltage excursions must be <u>disconnected within 1 second</u>.
- 2) Flicker 2% at the dedicated transformer.
- 3) Frequency < 5% Hz and removed in \leq .2 seconds
- 4) Harmonics < 5% sum of squares
- 5) Faults Remove DSG in < 1 second for utility fault
- 6) Power factor \geq .85

VIII. Dangerous Levels of Current



Figure 14. Effect of Current on Humans

IX. Capacitor Formulas

Nomenclature: $C = Capacitance in \mu F$

$$V = Voltage$$

A = Current
K = 1000

1) Capacitors connected in parallel: $C_{Total} = C_1 + C_2 + C_3 + - -$

2) Capacitors connected in series:

$$C_{\text{Total}} = \frac{C_1 \times C_2}{C_1 + C_2}$$

For two capacitors in series

 $C_{\text{Total}} = \frac{1}{\underbrace{\begin{array}{c} 1 \\ C_1 \end{array}}^{+} \underbrace{\begin{array}{c} 1 \\ C_2 \end{array}}^{+} \underbrace{\begin{array}{c} 1 \\ C_3 \end{array}}^{+} \underbrace{\begin{array}{c} -1 \\C_3 \end{array}}^{+} \underbrace{\begin{array}{c} -1 \\C_3 \end{array}}^{+} \underbrace{\begin{array}{c} -1 \\C_3 \end{array}}^{+} \underbrace{\begin{array}{c} -1 \\C_3 \end{array}}^{+} \underbrace{\end{array}}^{+} \underbrace{\end{array}}^$

For more than two capacitors in series

a.
$$X_c = \frac{10^6}{(2\pi f)C}$$

b.
$$X_c = 2653 \text{ at } 60\text{HZ} (1\mu\text{F} = 2653 \Omega)$$

b.
$$X_c = \frac{KV^2 \times 10^3}{KVAR}$$

a.
$$C = \frac{10^6}{(2\pi f) X_c}$$

b. C =
$$\frac{\text{KVAR x } 10^3}{(2\pi f)(\text{KV})^2}$$

5) Capacitive Kilovars

a. KVAR =
$$(2\pi f)C (KV)^2$$

10³

b. KVAR =
$$\frac{10^3 (KV)^2}{X_c}$$

ABB

6) Miscellaneous

a.	Power Factor =	Cos θ	KW
			KVA

Tan θ KVAR KW

X. European Practices

A. Primary



Figure 15. European / US Voltage Levels





B. Relays

- TMS Time multiplier setting (similar to time dial)
- CTU Earth fault relay set between 1 % and 16 % of rated current
- CDG 11 Standard overcurrent relay
- CDG 13 Very inverse
- CDG 14 Extremely inverse relay
- CTU 12 Definite time relay

C. Earth Fault Protection

- Based on the premise that all loads are 3 phase and balance
- Considers the effect of line capacitance mismatch
- Uses residual current

D. General

- Autoreclosure on overhead is normal
- Use normally open loop most of the time
- Even on a 3-wire system there may be some unbalance due to capacitors which must be considered when setting the earth relay
- Conventional relays will not operate for unearthed systems
- For ungrounded systems:
 - current and voltage unbalance must exceed a predetermined amount
 - phase angle must occur within a specified range (makes capacitor application difficult)
 - □ I (fault) is highly influenced by the capacitance of the network
- Maximum fault levels allowed are:

Table 7

kV	kA
33	25
22	20
11	20

- 11-kV system is mostly radial and underground
- 33-kV system is looped and mostly underground
- Most 4I5-volt transformers are I00 kVA or less and about 50% loaded

Table 8 - Distribution System Design Comparison

U.S.	Europe	
120/240	380 Wye/220, 4-wire. 416 Wye/240, 4-wire (UK)	
1-phase transformers heavily overloaded – 25 kVA typical.	Less load per home than U.S.	
4 homes/transformer fairly typical	3-phase xfrms >> \$ 1-phase	
Higher load density	Residential units in 300-500 kVA range	
Fuses are typically expulsion	5 to 10 radial, 3-phase, 4-wire secondary feeds, per transformer	
	No overload	
	Fuses are current limiting	
	100 to 200 dwellings per transformer	



Figure 17. 33 kV/11 kV Distribution

XI. Power Quality Data

A. Momentaries

Typical number of customer momentaries caused by the utility system ≈ 5 Typical number of customer momentaries for all causes ≈ 10

B. Sags

Typical number of customer sags caused by the utility system \approx 50 Typical number of customer sags for all causes \approx 350 **Voltage below .9 PU of nominal*

C. Power Quality Organizations

Committee/Standard	Activity	
Characterizing Power Quality/Power Quality Indices/General Power Quality		
Power Quality Standards coordinating committee	Coordinates all power quality standards activities	
SCC-22		
IEEE 1159	A number of task forces addressing different	
Monitoring Power Quality	aspects of power quality monitoring requirements and definitions	
IEEE 141	General guidelines for industrial commercial power	
Red Book	systems	
IEEE 241	General guidelines for commercial power systems	
Gray Book		
Harmonics		
IEEE P519A	Developing application guide for applying harmonic	
	limits	
Filter Design Lask Force	Guidelines for harmonic filter design	
Task Force on Harmonic Limits for Single Phase	Developing guidelines for applying harmonic limits	
Equipment	at the equipment level	
Voltage Sags/Momentary Interruptions		
IEEE 493	Industrial and commercial Power system Reliability	
Gold Book		
IEEE 1346	Evaluating compatibility of power systems for	
	industrial process controllers	
Steady State Regulation, Unbalance, and Flicker	•	



ANSI C84.1	Voltage rating for power systems and equipment
IEEE Flicker Task Force	Developing a coordinated approach for
	characterizing flicker
Wiring and Grounding/Powering Sensitive Equip	oment
IEEE 1100 Emerald Book	Guidelines for powering and grounding sensitive
	equipment
National Electric Code	Safety requirements for wiring and grounding
IEEE 142	Industrial and commercial Power System grounding
Green Book	
Transients	
OEEEA NSI C62	Guides and standards on surge protection
Distribution Systems/Custom Power Solution	
IEEE 1250 Distribution Power Quality Working	Guide on equipment sensitive to momentary
Group	voltage variations
IEEE 1409	Developing guidelines for application of power
Custom Power Task Force	electronics technologies for power quality
	improvement on the distribution system

D. Categories and Typical Characteristics of Power System Disturbances

Categories		Typical Duration	Typical Voltage Magnitude
Transients	Impulsive	nsec to msec	na
	Oscillatory	3 msec	0.8 pu
Short Duration Variations	Instantaneous Sag	.5 – 30 cycles	0.1 – 0.9 pu
·	Instantaneous Swell	.5 – 30 cycles	1.1 – 1.8 pu
	Momentary Interruption	0.5 cycles – 3 sec	Less than 0.1 pu
	Momentary Sag	30 cycles – 3 sec	0.1 – 0.9 pu
	Momentary Swell	30 cycles – 3 sec	1.1 – 1.4 pu
	Temporary Interruption	3 sec – 1 min	Less than 0.1 pu
	Temporary Sag	3 sec – 1 min	0.1 – 0.9 pu
	Temporary Swell	3 sec – 1 min	1.1 – 1.4 pu
Long Duration Variations	Sustained Interruption	Longer 1 minute	0.0 pu
	Undervoltage	Longer 1 minute	0.8 – 0.9 pu
	Overvoltage	Longer 1 minute	1.1 – 1.2 pu
Voltage Imbalance		Steady state	.5 – 2%
Waveform Distortion	DC Offset	Steady state	.05 – 2%
	Harmonics	Steady state	0 – 20%
	Inter-harmonics	Steady state	0 – 20%
	Notching	Steady state	NA
	Noise	Steady state	0 – 1%
Voltage Fluctuations		Intermittent	0.1 – 7%
Power Frequency Variations		Less than 10 sec	NA

Table 9

ABB

XII. Electricity Rates

For Medium Size Commercial and Industrial		
Utility	Commercial \$/kWh	Industrial \$/kWh
А	\$0.1067	\$0.0899
В	\$0.1761	\$0.0732
С	\$0.1672	\$0.1058
D	\$0.1482	\$0.0998
Е	\$0.1328	\$0.1039
F	\$0.1279	\$0.0720
G	\$0.1690	\$0.0950

Table 10

Table 11

Twelve Most Expensive Companies Investor-Owned Electric Utilities			
		Dec.'91 - Feb.'92	
Company	State	Avg. Cost \$/kWh*	National Rank
Long Island Lighting Co.	New York	\$0.156	1
Philadelphia Electric Co.	Pennsylvania	\$0.152	2
Pennsylvania Power Co.	Pennsylvania	\$0.148	3
Duquesne Light Co.	Pennsylvania	\$0.146	4
Consolidated Edison Co.	New York	\$0.137	5
Western Mass. Electric Co.	Massachusetts	\$0.137	6
Hawaii Electric Co.	Hawaii	\$0.136	7
Nantucket Electric Co.	Massachusetts	\$0.135	8
Commonwealth Electric Co.	Massachusetts	\$0.131	9
Orange & Rockland Utilities Inc.	New York	\$0.130	10
Citizens Utilities Co. – Kauai Div.	Hawaii	\$0.125	11
United Illuminating Co.	Connecticut	\$0.124	12
*For monthly residential sales of 500 kWh.			
Source: National Association of Regulatory Utility Commissioners			

Twelve Least Expensive Companies Investor-Owned Electric Utilities			
		Dec.'91 - Feb.'92	
Company	State	Avg. Cost \$/kWh*	National Rank
Washington Water Power Co.	Idaho	\$0.041	191
Pacific Power & Light Co.	Washington	\$0.043	192
Washington Water Power Co.	Washington	\$0.044	189
ldaho Power Co.	Oregon	\$0.047	188
ldaho Power Co.	ldaho	\$0.047	187
Kentucky Utilities Co.	Kentucky	\$0.051	186
Portland General Elec. Co.	Oregon	\$0.052	185
Puget Sound Power & Light Co.	Washington	\$0.053	184
Potomac Electric Power Co.	Dist. of Col.	\$0.054	183
Minnesota Power & Light Co.	Minnesota	\$0.054	182
Pacific Power & Light Co.	Oregon	\$0.055	181
Kingsport Power Co.	Tennessee	\$0.056	180
*For	monthly residential sales	of 500 kWh.	
Source: Natio	onal Association of Regula	atory Utility Commissioners	

Table 12

XIII. Costs

A. General

1) Annual system capacity:

Generation:	\$ 704/kW
Transmission:	\$ 99/kW
Distribution:	\$ 666/kW
Total:	\$1469/kW

2) Cost of capacitors (installed)

Substations:	\$ 9/kVAR
Line:	\$ 5.5/kVAR
Padmounted:	\$ 21/kVAR

- **3)** Transformers (installed)
 - a. Single phase padmounts (installed)

	12.5 kV (loop feed)	34.5 kV (loop feed)
25 kVA	\$2552	\$3119
50 kVA	\$2986	\$3931
75 kVA	\$3591	\$4725
100 kVA	\$4972	\$5728

b. Three Phase Padmounts

	12.5 kV (loop feed)	34.5 kV (loop feed)
75 kVA	\$ 7,749	\$10,584
150	\$ 9,450	\$11,605
300	\$11,718	\$15,574
500	\$13,608	\$20,034
750	\$21,357	\$21,377
1000	\$25,515	\$28,350
1500	-	\$40,824
2500	-	\$50,841

NOTE: Above costs include necessary cable terminations, pads, misc. material and transformer, but no primary or secondary cable.

4) Substation costs (includes land, labor, and material)

a.	115-13.2kV, 20/37.3 MVA, 4 feeder substation	\$3,348,000
b.	35-12.5 kV, 12/16/20 MVA, 2 feeder substation	\$1,026,000
C.	115-35kV, 60/112 MVA, 5 feeder substation	\$4,050,000
d.	230-13.2 kV, 27/45 MVA, 5 feeder substation	\$3,960,000
e.	230-34.5 kV, 60/112 MVA, 5 feeder substation	\$5,040,000

5) Miscellaneous costs:

a. Cable (approximate)

٠	Mainline, conduit	\$	90/ft
٠	Mainline, D.B.	\$	38/ft
٠	Lateral, conduit	\$	63/ft
		•	~ ~ ~ ~

- Install transformer \$ 2,698
- Change out transformer \$ 2,822 •
- •
- •
- Install 3Ø switch
 \$ 20,871

 Replace 3Ø switch
 \$ 11,203

 Install 1Ø fuse switch
 \$ 11,367
 •

6) Cost of replacing cable:

- 1Ø \$180/ft. a.
- 3Ø \$360/ft. b.
- 7) Elbows (installed) - \$111 each

XIV. Reliability Data

Table 13

Failure Rate Data			
Component	Failure Rate		
Primary Cable (polyethylene)	6/100 mi-yr (conductor miles)		
Secondary Cable (polyethylene)	10/100 mi-yr (circuit miles)		
Transformers, single phase, padmounted	0.4%/yr		
Transformers, three-phase, padmounted	0.62%/yr		
Transformers, single phase, subsurface	0.3%/yr		
Switches, oil, subsurface	0.12%/yr		
Switches, air, padmounted	0.12%/yr		
Fuse cabinet, single phase, padmounted	0.1%/yr		
Fuse cabinet, three-phase, padmounted	0.2%/yr		
Primary splices, rubber molded	.01%/yr		
Elbows:			
Rubber molded, loadbreak	.06%/yr		
Rubber molded, non-loadbreak	.06%/yr		
Tees, 600 amp	.02%/yr		

Typical values for customer based indices are:

- SAIDI 96 min/yr.
 SAIFI 1.18 interruptions/yr.
 CAIDI 81.4 min/yr.

XV. Industrial and Commercial Stuff

Introduction

Utility engineers have historically needed to know a lot about their own system and very little about their customers system and loads. Competitive times and the emphasis on power quality have forced the utility engineer to venture to the "other side of the meter" to address the power related concerns and problems of specific industrial processes and components. The purpose of this section is to address some of the more commonly encountered terminology, equipments and problems that the utility distribution engineer generally has a hard time finding.

Motors

a. Major Categories of Motors

Alternating Current Types <u>Three-Phase</u> Induction Synchronous

Single-Phase

Induction-Run, Capacitor Start Induction-Run, Split Phase Start Shaded-Pole Universal (Commutator) Repulsion

Direct Current Types

Shunt-Characteristic:	Electromagnetic Field
Shunt-Characteristic:	Permanent Magnet Field
Series-Characteristic:	Series Field Only
Compound Wound	

b. KVA/Hp Conversions (at full load)

	<u>KVA / HP</u>
Induction 1 - 100 Hp	1.0
Induction 101 - 1000 Hp	0.95
Induction > 1000 Hp	0.9
Synchronous 0.8 pf	1.0
Synchronous 0.9 pf	0.9
Synchronous 1.0 pf	0.8

c. Reduced-voltage Starters

Table 14

Reduced-Voltage Starter Type	Line Current As % Of Full-Voltage Starting
Autotransformer – 50% tap	30%
Autotransformer – 65% tap	47%
Autotransformer – 80% tap	69%
Wye-delta	33%
Part-Winding	70%
Primary Resistor – 80% tap	80%

Primary R	esistor –	65%	tap
-----------	-----------	-----	-----

65%

d. Characteristics of Motors

DC Motors

- Advantage of DC Motor is that the torque-speed characteristic can be varied over a wide range and still have high efficiency
- 3 Basic Types Shunt, Series and Compound
- **Shunt** In this motor the field current is independent of the armature having been diverted (shunted) through its own separate winding. Increasing the field current actually causes the motor to slow down. Torque and power however are higher.
- Series The series motor is identical in construction to the shunt motor except the field is connected in series with the armature. At startup, armature current is high, so flux is high and torque is high. If load decreases, speed goes up. Series motors are for high torque, low speed applications such as the starter motor of a car or the motors used for electric locomotives.
- **Compound** A compound motor carries both a series field and a shunt field. The shunt field is always stronger. As load increases, the shunt field remains the same but the series field increases. At no load it looks like a shunt motor.

The diagram shown below illustrates the basic characteristics of these motors:



Figure 18 - Typical speed versus load characteristics of various dc motors

Induction Motors

- Most frequently used in industry (simple, rugged and easy to maintain)
- Essentially constant speed from 0 to full load
- Not easily adapted to speed control
- Parts:
 - Stationary stator
 - Revolving rotor (slip ring at end)
 - Conventional 3 phase winding
 - Squirrel-cage windings (copper bars shorted at end)

The characteristics of the induction motor are illustrated below:



Figure 19

Synchronous Motors

- The most obvious characteristic of a synchronous motor is its strict synchronism with the power line frequency.
- Its advantage to the industrial user is its higher efficiency and low cost in large sizes
- Biggest disadvantage is added complications of motor starting.
- A synchronous motor is identical to a generator of the same rating.
- Synchronous motors are only selected for applications with relatively infrequent starts since starting is more difficult and usually requires the use of induction (squirrel cage) motor.

e. Adjustable-Speed Drives

- Adjustable speed drives have the **advantage** of being both efficient and reliable
- Used for compressors, pumps, and fans that have variable-torque requirements
- Six basic types:
 - DC drive with DC motor
 - Voltage-source inverter with induction motor
 - Slip-energy recovery system with wound-rotor motor
 - Current-source inverter with induction motor
 - Load-commutated inverter with synchronous motor
 - Cycloconverter drive for either a synchronous or an induction motor

The figure, shown below, is a one line diagram for a typical current-source inverter. The current-source inverter has a phase controlled rectifier that provides a DC input to a six-step inverter. The reactor provides some filtering. Control of the inverter serves to regulate current and frequency, rather than voltage and frequency as with the voltage-source inverter.



Figure 20 – Typical current-source inverter (A) and one with a 12-pulse power conversion unit (B) required by larger motors

XVI. Maxwell's Equations

When in doubt, you can always go back and derive whatever you need to know using Maxwell's equations (that's what my professor told me right!!!!!!) So here goes:

Gauss' law for electric fields

$$\oint E \bullet dA = \frac{Q}{\varepsilon_0}$$

Gauss' law for magnetic fields

$$\oint B \bullet dA = 0$$

Generalized Ampere's law

$$\oint B \bullet ds = \mu_0 I + \mu_0 \varepsilon_0 \frac{d}{dt} \iint_s E \bullet dA$$

Faraday's law

$$\oint E \bullet ds = -\frac{d}{dt} \iint_{s} B \bullet dA$$

Got that!!!!!!!

EXPERIENCE

Mr. Burke joined ABB in 1997 as an Institute Fellow at ABB's Electric systems Technology Institute. He is recognized throughout the world as an expert in distribution protection, design, power quality and reliability.

Mr. Burke began his career in the utility business with the General Electric Company in 1965 training and taking courses in generation, transmission and distribution as part of GE's Advanced Utility Engineering Program. In 1969, he accepted a position as a field application engineer in Los Angeles responsible for transmission and distribution system analyses, as well as generation planning studies for General Electric's customer utilities in the Southwestern states. In 1971 he joined GE's Power Distribution Engineering Operation in New York where he was responsible for distribution substations, overcurrent and overvoltage protection, and railroad electrification for customers all over the world. During this period he was involved with the development of the MOV "riser pole" arrester, the Power Vac Switchgear, the static overcurrent relay and distribution substation automation.

In 1978 Mr. Burke accepted a position at Power Technologies Inc. (PTI) where he continued to be involved with virtually all distribution engineering issues. During this period he was responsible for the EPRI distribution fault study, the development of the first digital fault recorder, state-of-the-art grounding studies, and numerous lightning and power quality monitoring studies. In the area of railroad electrification he was coauthor of the EPRI manual on "Railroad Electrification on Utility Systems" as well as project manager of system studies for the 25 to 60 Hz conversion of the Northeast Corridor. Until his departure in 1997, he was manager of distribution engineering.

Institute Fellow

He has authored and co-authored over 85 technical papers, including two prize papers. He is the author of the book "Power Distribution Engineering: Fundamentals & Applications". He is author of the last two revisions to the chapter on Distribution Engineering in the "Standard Handbook for Electrical Engineering."

EDUCATION

BSEE - Univ. of Notre Dame MSIA – Union College – Thesis: "Reliability and Availability Analysis of Direct Buried Distribution Systems" PSEC – GE (Schenectady)

PROFESSIONAL ACTIVITIES

IEEE

Chair: Dist. Neutral Grounding Chair: Voltage Quality Past Chair: Dist. Subcommittee Member – T&D Committee Member–Surge Protective Device Committee

ACHIEVEMENTS & HONORS

IEEE

Fellow (1992) Standards Medallion (1992) 2 Prize Papers The 1996 Award for: "Excellence in Power Distribution Engineering" Distinguished Lecturer in Power Quality

JAMES J. BURKE

Technical Papers

<u>G.E.</u>

- "An Availability and Reliability Analysis of Direct Buried and Submersible Underground Distribution Systems," *IEEE Transactions* Conference paper, Underground Conference Detroit, Mich., June 1970 (co-author: R. H. Mann)
- "How Do You Serve 3 Phase Loads Underground," *Electrical World*, June 1970 (co-authors: R. H. Mann, and F. Tabores).
- 3. "Railroad Electricification" *Electric Forum Magazine,* June 1976 (co-author: J. H. Easley).
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